



Consensus & Polarization in Constrained Opinion Dynamics

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Emergence of diversity is a complex problem in life and behavioural sciences: what are the main features to be incorporated in basic mathematical models? How to treat those models?

- Basic and unifying principles of evolutionary dynamics
- The 2-state voter model
- The 3-species constrained voter model
 - The model and solution method
 - The fixation probabilities
 - The mean fixation times
- Conclusion

Basic principles of evolutionary dynamics

Basic and unifying principles for modelling evolutionary dynamics:

- Dynamics proceeds by imitation: traits/strategies/individuals die and reproduce (are copied) at each time step.
- Selection: successful traits/strategies/individuals spread at the expense of the less fit
- Population is finite and there are demographic fluctuations (“genetic/random” drift)
- Mutations: traits/strategies/individuals can spontaneously switch with some rate
- Migration: traits/strategies/individuals can move and spread in space (“islands”, “patches”,...)

These principles transcend biology (genetics, ecology) and behavioural science (evolutionary game theory and opinion dynamics).

Key questions: how is diversity maintained?

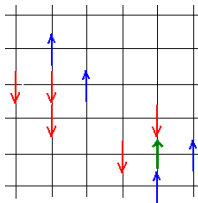
In opinion dynamics: when is there consensus / cultural diversity?

Paradigmatic opinion dynamics model: **the voter model** (closely related to the Moran model and other model of imitation dynamics))

2-state Voter Model

Voter Model (Liggett 1985): Basic/paradigmatic two-state model where individuals are either in $+1$ (\uparrow) or -1 (\downarrow) opinion state

Dynamics: at each time step an individual adopt the opinion state of a randomly picked neighbour



N voters on a complete graph, initial fraction of $+1$ is x :

- Consensus is always reached
- Probability to reach $+1$ and -1 consensus is x and $1 - x$, resp.
- Mean time to attain consensus is $T \sim N$

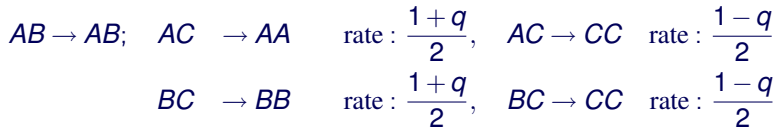
2-state VM cannot explain the emergence of cultural diversity

Axelrod (1997) & bounded comprise models (Deffuant et al., 2000):

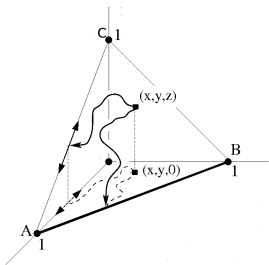
consensus limited by **incompatibility** \Rightarrow *cultural diversity* (?)

The 3-species constrained voter model

N individuals of 3 species, A, B and C . A 's (**leftists**) and B 's (**rightists**) are *incompatible* (don't interact), but interact with **centrists** C 's



4 possible outcomes: consensus with A, B or C , or frozen mixture of A and B (**polarization**) \Rightarrow **What is the (fixation) probability and mean time for each of these events starting with densities $x, y, z = 1 - x - y$ of A, B and C ? Here, $0 < |q| \leq 1$.**



- $q > 0$: bias towards **polarization** (extremisms), with absorbing line $x + y = 1$
- $q < 0$: bias towards **centrism** (appeasement)
- $q = 0$: driven by fluctuations
[Vazquez & Redner in J.Phys.A **37**, 8479 (2004)]

The analysis of complex systems requires the complementary use of various mathematical tools

- Nonlinear dynamics and theory of ODEs & PDEs: mean field, separation of variables
- Individual-based modelling: stochastic processes, intrinsic noise
- Mapping onto related models across disciplines (here, population genetics, evolutionary game theory, quantum mechanics)
- Stochastic simulations (here, Gillespie algorithm)

Other related approaches (not in this work):

- Theory of network dynamics
- Spatially-extended interacting particle systems
- Theory of pattern formation

3-species constrained voter model: Mean-field

Mean field picture: all fluctuations are neglected (assume that $N = \infty$)
Rate equations for density a of A 's and b of B 's (with $c = 1 - a - b$):

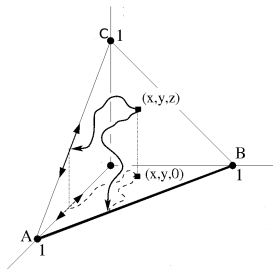
$$\frac{d}{dt}a = \frac{(1+q)}{2}ac - \frac{(1-q)}{2}ac = qa(1-a-b), \quad \frac{d}{dt}b = qb(1-a-b)$$

$$a(t) = \frac{xe^{qt}}{1-(x+y)(1-e^{qt})}, \quad b(t) = \frac{ye^{qt}}{1-(x+y)(1-e^{qt})}$$

Ratio $a/b = x/y$ is conserved. 3 absorbing fixed points:

$(a, b, c) \in \{\mathcal{A} = (1, 0, 0), \mathcal{B} = (0, 1, 0), \mathcal{C} = (0, 0, 1)\} + (\text{polarization})$

line of fixed points $\mathcal{AB} = (a, 1-a, 0)$, with $0 < a < 1$



- When $q > 0$:
 $a \rightarrow \frac{x}{x+y}, b \rightarrow \frac{y}{x+y}, c \rightarrow 0$
(polarization)
- When $q < 0$:
 $a \rightarrow 0, b \rightarrow 0, c \rightarrow 1$
(centrism)

3-species constrained VM: Individual-based approach

When population is finite, $N < \infty$, fluctuations alter the mean field predictions: polarization is likely when $q > 0$, but still finite probability to reach a consensus; the opposite happens when $q < 0$

Finite and well-mixed (“complete graph”) population \Rightarrow **Stochastic formulation:**

Probability $P^{\mathcal{A}\mathcal{B}}$ that the final state is a frozen mixture of extremists obeys the backward master equation (ME):

$$\begin{aligned} & (T_x^+ + T_x^- + T_y^+ + T_y^-)P^{\mathcal{A}\mathcal{B}}(x, y) = \\ & T_x^- P^{\mathcal{A}\mathcal{B}}(x - \delta, y) + T_x^+ P^{\mathcal{A}\mathcal{B}}(x + \delta, y) \\ + & T_y^- P^{\mathcal{A}\mathcal{B}}(x, y - \delta) + T_y^+ P^{\mathcal{A}\mathcal{B}}(x, y + \delta) \end{aligned} \quad (1)$$

+ boundary conditions. With $T_\xi^\pm \equiv (1 \pm q)\xi(1 - x - y)/2$, $\xi \in (x, y)$ and $\delta = N^{-1}$

Analytical progress: expand the ME to 2nd order in $\delta \rightarrow$ Fokker-Planck equation. Analogy with models of population genetics and evolutionary game theory

3-species voter model: Mathematical treatment (II)

By Taylor expansion of the ME (1):

$$\left\{ 2s[x\partial_x + y\partial_y] + x\partial_x^2 + y\partial_y^2 \right\} P^{\mathcal{A}\mathcal{B}}(x, y) = 0, \quad (2)$$

with $P^{\mathcal{A}\mathcal{B}}(x, 0) = P^{\mathcal{A}\mathcal{B}}(0, y) = 0$ and $P^{\mathcal{A}\mathcal{B}}(x, 1-x) = 1$ and $\mathbf{s} \equiv \mathbf{Nq}$

Equation is **separable**. With polar coordinates

$\sqrt{x} = \rho \cos \theta, \sqrt{y} = \rho \sin \theta$: $P^{\mathcal{A}\mathcal{B}} = \sum_n c_n R_n(\rho) u_n(\theta) \sin(2\theta)$, yielding

$$\rho^2 \frac{d^2 R_n}{d\rho^2} + \rho \frac{dR_n}{d\rho} [4s\rho^2 - 1] - \lambda_n R_n = 0$$

$$\frac{d^2 u_n}{d\theta^2} - \frac{3}{4} \left(\frac{1}{\sin^2 \theta} + \frac{1}{\cos^2 \theta} \right) u_n + (1 + \lambda_n) u_n = 0$$

BCs: $P^{\mathcal{A}\mathcal{B}}(\rho = 0, \theta) = 0$ and $P^{\mathcal{A}\mathcal{B}}(\rho = 1, \theta) = 1$

Mapping onto a stationary Schrödinger equation with Pöschl-Teller potential $\Rightarrow \lambda_n = 4(n+1)(n+2)$

$$P^{\mathcal{A}\mathcal{B}}(x, y) = 2 \sqrt{\frac{xy}{x+y}} e^{s(1-x-y)} \sum_{\text{nodd}} \frac{2n+1}{n(n+1)} P_n^1 \left(\frac{x-y}{x+y} \right) \frac{I_{n+1/2}(s(x+y))}{I_{n+1/2}(s)}$$

I_n 's and P_n^1 's: Modified Bessel functions & associated Legendre Polynomials

3-species voter model: Mathematical treatment (III)

Probability density along polarization line is $F_a^{\mathcal{A}\mathcal{B}}$, with
 $P^{\mathcal{A}\mathcal{B}}(x, y) = \int_0^1 da F_a^{\mathcal{A}\mathcal{B}}(x, y) \Rightarrow F_a^{\mathcal{A}\mathcal{B}}$ obeys (2) with BC
 $F_a^{\mathcal{A}\mathcal{B}}(x, 1-x) = \delta(a-x)$

Fixation probabilities $P^{\mathcal{I}}(x, y)$ in states $\mathcal{I} \in \{\mathcal{A}, \mathcal{B}, \mathcal{C}, \mathcal{A}\mathcal{B}\}$ satisfy

$$P^{\mathcal{A}}(x, y) + P^{\mathcal{B}}(x, y) + P^{\mathcal{A}\mathcal{B}}(x, y) = a + b = 1 - P^{\mathcal{C}}(x, y) = \frac{1 - e^{-2s(x+y)}}{1 - e^{-2s}},$$

with $P^{\mathcal{B}}(x, y) = P^{\mathcal{A}}(y, x)$. Furthermore, steady state densities are:

$$a = P^{\mathcal{A}}(x, y) + \int_0^1 da' a' F_{a'}(x, y)$$

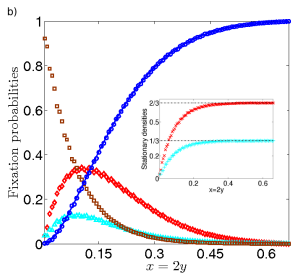
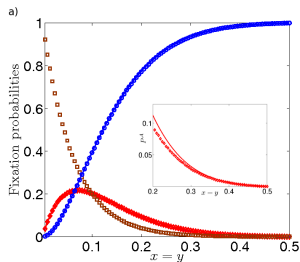
$$b = P^{\mathcal{B}}(x, y) + P^{\mathcal{A}\mathcal{B}}(x, y) - \int_0^1 da' a' F_{a'}(x, y)$$

- When $s = N|q| \gg 1$: drift dominates over diffusion terms \Rightarrow like mean field
- When $s \ll 1$: drift negligible $\Rightarrow \approx$ like the unbiased case (JPA37, 8479 (2004))
- **Effective (interesting) competition arises when $s = Nq = \mathcal{O}(1)$**

Fixation probabilities when $s = Nq > 0$

Top: Fixation probabilities for $s > 0$ as functions of x (for $N = 200, s = 4$, i.e. $q = 0.02$):
 P^A (\diamond), P^B (\triangle), P^C (\square); P^{AB} (\circ)
Solid line: analytical sol. of (2)

Bottom: same as above, but with $x = 2y$.
Inset: final densities of species A (\times) and B ($+$) as functions of $x = 2y$.



Fixation probabilities when $s < 0$

Top: as before, with $s = -4$

Comparison with analytics:

Solid: solution of (2)

Dashed:

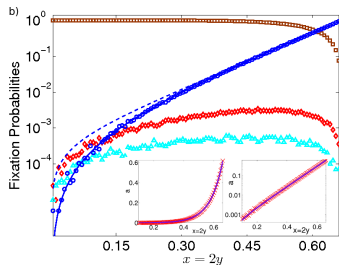
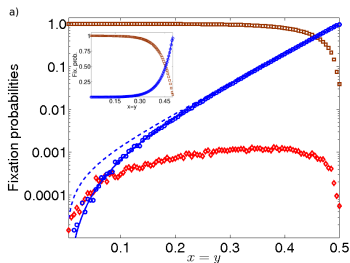
$$P^{AB} \approx 1 - P^C = \frac{e^{2|s|(x+y)} - 1}{e^{2|s|} - 1}$$

Bottom: as above, but with $x = 2y$.

Inset: stationary density of A (\times)

as function of $x = 2y$ compared

with analytics



3-species voter model: Mathematical treatment (IV)

The unconditional mean fixation time (MFT) τ to reach *any* of the system's absorbing states obeys the backward Fokker-Planck equation with boundary conditions

$\tau(1, 0) = \tau(0, 1) = \tau(0, 0) = \tau(a, 1 - a) = 0$. With $w \equiv x + y$:

$$\begin{aligned} \mathcal{L}_{\text{bFP}} &= \frac{w(1-w)}{N} \left[2s \frac{d}{dw} + \frac{d^2}{dw^2} \right] \\ \mathcal{L}_{\text{bFP}}(w)\tau(w) &= -1, \quad \text{with } \tau(0) = \tau(1) = 0 \Rightarrow \end{aligned} \quad (3)$$

Useful mapping with a population genetics model (s is “selection strength”). Solution (for $w = 1/2$):

$$\begin{aligned} \tau &= Nf_{\tau}(s, w = 1/2) = \frac{N}{s(1+e^s)} \left[e^{2s} \text{Ei}(-2s) + (e^s - 1) \ln(2|s|) \right] \\ &+ \frac{N}{2se^s(1+e^s)} \left[e^s(e^s - 1)\gamma_{\text{E}} + \text{Ei}(s) - \text{Ei}(2s) \right] \\ &+ \frac{N}{2s(1+e^s)} \left[2\text{Ei}(s) - 2e^s(e^s + 1)\text{Ei}(-s) \right], \end{aligned}$$

where $\text{Ei}(x) \equiv \int_{-\infty}^x \frac{e^t}{t} dt$ and $\gamma_{\text{E}} = 0.5772\dots$

Unconditional & Conditional Mean Fixation Times

The unconditional MFT $\tau = \tau(x + y)$:

- is a function of initial density of extremists ($x + y$)
- scales linearly with N
- symmetry: invariant under $(s, x + y) \rightarrow (-s, 1 - x - y) \Rightarrow$
 $\tau(x + y) = Nf_\tau(s, x + y) = Nf_\tau(-s, 1 - x - y)$
- f_τ has an inverted u-shape dependence on $w = x + y$

The *conditional* mean fixation times $\tau^{\mathcal{S}}$, to reach the specific absorbing state $\mathcal{S} \in (\mathcal{A}, \mathcal{B}, \mathcal{C}, \mathcal{AB})$ obey:

$$\mathcal{L}_{\text{bFP}}(x, y)[P^{\mathcal{S}}(x, y)\tau^{\mathcal{S}}(x, y)] = -P^{\mathcal{S}}(x, y) \text{ (+BC's),}$$

where the $P^{\mathcal{S}}(x, y)$'s are the fixation probabilities

- All $\tau^{\mathcal{S}}$'s are found to scale linearly with N
- The $\tau^{\mathcal{S}}$'s do not depend on the sign of s (*more noisy when $s < 0$*)
- The extremists' MFTs, $\tau^{\mathcal{A}}$ and $\tau^{\mathcal{B}}$, are always the longest MFTS

Mean Fixation Time

Normalized unconditional MFT
 τ/N (\times) compared with sol. of (3)
(solid)

Normalized conditional MFTs

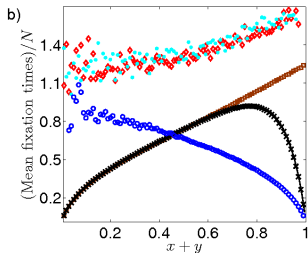
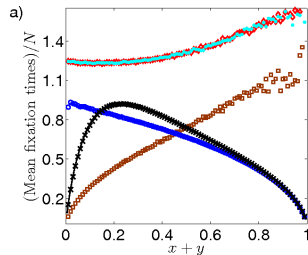
τ^A/N (\diamond)

τ^B/N (\bullet)

τ^C/N (\square)

τ^{AB}/N (\circ).

$N = 200$, $x = y$, $s = 4$ (top) and
 $s = -4$ (bottom). Average is over
 2×10^5 samples.



Understanding the origin and maintenance of diversity in evolutionary dynamics

Seek of consensus & incompatibility: relevant ingredients for cultural diversity in opinion dynamics?

Study of a mathematically amenable model: the 3-state constrained voter model:

- Possible outcomes: consensus with extremists, consensus with centrists, polarization of extremism (“leftists” and “rightists” coexist)
- Bias (\sim selection) \rightarrow nonlinearity. Finite population \rightarrow intrinsic noise
- Small bias ($q \sim N^{-1}$, “weak selection”): subtle competition between drift and fluctuations
- Combination of mathematical methods to tackle the problem

How relevant is all of this?

- Realistic ingredients: mutations, dispersal, network
- **Would it be possible to validate a variant of the model using real data?**