GENERALIZED LAMÉ OPERATORS

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ABSTRACT. We introduce a class of multidimensional Schrödinger operators with elliptic potential which generalize the classical Lamé operator to higher dimensions. One natural example is the Calogero–Moser operator, others are related to the root systems and their deformations. We conjecture that these operators are algebraically integrable, which is a proper generalization of the finite-gap property of the Lamé operator. Using earlier results of Braverman, Etingof and Gaitsgory, we prove this under additional assumption of the usual, Liouville integrability. In particular, this proves the Chalykh–Veselov conjecture for the elliptic Calogero–Moser problem for all root systems. We also establish algebraic integrability in all known two-dimensional cases. A general procedure for calculating the Bloch eigenfunctions is explained. It is worked out in detail for two specific examples: one is related to B_2 case, another one is a certain deformation of the A_2 case. In these two cases we also obtain similar results for the discrete versions of these problems, related to the difference operators of Macdonald–Ruijsenaars type.

1. INTRODUCTION

In this paper we consider higher-dimensional analogues of the classical Lamé operator

$$(1.1) \qquad L = -\frac{d^2}{dz^2} + m(m+1)\wp(z), \qquad m \in \mathbb{Z}_+ .$$

Here $\wp(z) = \wp(z|1,\tau)$ is the Weierstrass $\wp$-function with periods $1, \tau$. More generally, we are interested in multivariable analogues of the so-called **elliptic algebro-geometric operators** $L = -d^2/dz^2 + u(z)$, which appeared in the finite-gap theory initiated in 70's by Novikov [1]. This theory provides a beautiful interplay between the spectral theory and algebraic geometry, and the Lamé operator is the simplest and best known member of this family of operators (see [2] for a survey). Since then there have been several attempts to generalize some parts of that theory to higher dimensions, most notably [3, 4], see also [5, 6, 7]. We should stress, however, that in general this leads to differential operators with *matrix coefficients*. On the other hand, in [8] it was suggested to consider the quantum elliptic Calogero–Moser problem and its versions related to the root systems [9] as natural multidimensional analogues of the Lamé operator. More specifically, a conjecture from [8] says that for integer values of the coupling parameters the corresponding Schrödinger operators are *algebraically integrable* (this is a proper generalization of the properties of the algebro-geometric operators to higher dimensions, see [10, 11] and Section 3 below). For the rational and trigonometric versions of the Calogero–Moser problem

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this was proved in [10]. Elliptic version, however, turned out to be more difficult: until now it was known for A_n case only, due to [11].

One of the results of the present paper is a proof of that conjecture of [8] for all root systems. In fact, our approach applies to a wider class of Schrödinger operators, which is an elliptic version of the class introduced in [12], see also [13]. Their singularities are the second order poles along a set of hyperplanes satisfying some special conditions, which encode the *triviality of the local monodromy* around each of the poles. We call the corresponding Schrödinger operators the **generalized Lamé operators**. The Calogero–Moser operators with integer coupling parameters give particular examples of such operators. Our main result says that for a generalized Lamé operator its algebraic integrability follows from the usual, Liouville integrability (in a slightly stronger sense). The proof uses a criterion from [11], based on differential Galois theory. In dimension one we recover in this way the main result of [14]. For the elliptic Calogero–Moser problem the complete integrability was proved (for all root systems) by Cherednik [15], and this allows us to prove the conjecture of [8].

A complete description of all generalized Lamé operators is an open problem. All known (irreducible) examples in dimension > 1 are related to the root systems and their deformations which appeared in [13, 16]; we list them all in Section 4. We conjecture that they are all algebraically integrable. Using our main result, we check this for all two-dimensional examples, since the complete integrability is relatively easy to work out in that case.

One important property of the algebraically integrable operators is that their eigenfunctions can be calculated explicitly (at least, in principle). In section 5 we explain how to find the Bloch eigenfunctions for a given integrable generalized Lamé operator, in particular, for the elliptic Calogero–Moser problem. As a result, we will see that the Bloch solutions are parametrized by the points of an algebraic variety, which is a covering of a product of elliptic curves (in a perfect agreement with the situation in dimension one, due to Krichever [17]). Let us mention that for the elliptic Calogero–Moser problem (in the A_n case) the Bloch eigenfunctions were calculated by Felder and Varchenko [18]. Our procedure is different and more general (at cost of being less effective). We also explain how these Bloch solutions can be used to construct the discrete spectrum eigenstates for the Calogero–Moser problem.

In the last three sections of the paper we consider two particular examples of the generalized Lamé operators in dimension 2, for which we make the formulas for the Bloch solutions very explicit. The first example is

$$(1.2) \qquad L = -\Delta + 2\wp(x) + 2\wp(y) + 4\wp(x-y) + 4\wp(x+y) \, .$$

This is a special case of the elliptic Calogero–Moser problem of the B_2-type. Our second example is

$$(1.3) \qquad L = -\Delta + 2\wp(x) + 2(a^2 + b^2)\wp(ax + by) + 2(\overline{a}^2 + \overline{b}^2)\wp(\overline{a}x + \overline{b}y) \, ,$$

$$a = \frac{-1 + i\sqrt{3}\sin\alpha}{2} \, , \qquad \overline{a} = \frac{-1 - i\sqrt{3}\sin\alpha}{2} \, , \qquad b = -\overline{b} = \frac{i\sqrt{3}\cos\alpha}{2} \, ,$$

where α is a complex parameter. Such operator was considered by Hietarinta [19] who showed that it admits a commuting operator of order 3. Its rational version $\wp(z) = z^{-2}$ corresponds to a specific choice of the parameters in the family of

two-dimensional Schrödinger operators introduced by Berest and Lutsenko [20] in connection with Huygens' Principle (see section 4 of [13] for details). Note that the potential in (1.3) is real-valued (for real x, y) if α is real and the period τ is pure imaginary.

It is more convenient to work with the following 3-dimensional version of (1.3):

$$(1.4) \quad L = -\partial_1^2 - \partial_2^2 - \partial_3^2 + 2(a_1^2 + a_2^2)\wp(a_1 x_1 - a_2 x_2)$$
$$+ 2(a_2^2 + a_3^3)\wp(a_2 x_2 - a_3 x_3) + 2(a_3^2 + a_1^2)\wp(a_3 x_3 - a_1 x_1) \,,$$

where $a_1^2 + a_2^2 + a_3^2 = 0$, $\partial_i = \partial/\partial x_i$. Then it is easy to see that L commutes with the operator

$$L_0 = a_1^{-1}\partial_1 + a_2^{-1}\partial_2 + a_3^{-1}\partial_3$$

and after restriction to the plane

$$a_1^{-1}x_1 + a_2^{-1}x_2 + a_3^{-1}x_3 = 0$$

it reduces to the operator (1.3) with proper a, b.

We calculate explicitly the Bloch eigenfunctions of the operators (1.2), (1.4). Notice a certain similarity between our approach and the one used by Inozemtsev for A_2 case [21]. Let us also mention that in dimension two there is a nice theory of Schrödinger operators which are finite-gap at a fixed energy level, see [22, 23]. It would be interesting to analyze our results from that point of view.

In the last two sections we also calculate the Bloch solutions for the discrete versions of (1.2), (1.4), which are given by certain difference operators of Macdonald–Ruijsenaars type. This raises a natural question about generalizing our results to the difference setting. We hope to return to this problem in future.

2. Generalized Lamé operators

Let $V = \mathbb{C}^n$ be a complex Euclidean space with the scalar product denoted by $(\, , \,)$, and $\mathcal{A} = \{\alpha\}$ be a given finite set of affine-linear functions on V. Let us consider a Schrödinger operator

$$(2.1) \qquad L = -\Delta + u(x) \,, \qquad \Delta = \partial^2/\partial x_1^2 + \cdots + \partial^2/\partial x_n^2 \,,$$

with the elliptic potential u of the following form:

$$(2.2) \qquad u(x) = \sum_{\alpha \in \mathcal{A}} c_\alpha \wp(\alpha(x)|\tau) \,.$$

Here $\wp(z|\tau)$ is the Weierstrass $\wp$-function with the periods $1, \tau$, $\mathrm{Im}(\tau) > 0$, and $c_\alpha \in \mathbb{C}$ are the parameters which will be specified later (below we will mostly suppress τ, denoting $\wp(z|\tau)$ simply by $\wp(z)$). Each of the functions $\alpha(x)$ in standard coordinates on V looks as

$$\alpha(x) = a_0 + a_1 x_1 + \cdots + a_n x_n \,,$$

so α is, effectively, a pair (α_0, a_0) where $a_0 = \alpha(0) \in \mathbb{C}$ and $\alpha_0 = \mathrm{grad}\alpha = (a_1, \ldots, a_n)$. We assume that each α_0 is non-isotropic (co)vector, i.e. $(\alpha_0, \alpha_0) = a_1^2 + \cdots + a_n^2 \neq 0$. Let us project $\mathcal{A}$ onto V^*, $\alpha \mapsto \alpha_0$, denoting by $\mathcal{A}_0$ the resulting set.

We want u to be periodic, more precisely, we assume that the lattice $\mathcal{M} \subset V^*$, generated over $\mathbb{Z}$ by the set $\mathcal{A}_0$, has rank $\leq n$. For simplicity, let us assume that $\mathrm{rk}\mathcal{M} = n$ (the general case can be reduced to that by passing to the factor space $V/\mathrm{Ann}\mathcal{M}$). In that case the lattice $\mathcal{L} + \tau\mathcal{L}$ is the period lattice for u, with $\mathcal{L} := \mathrm{Hom}(\mathcal{M}, \mathbb{Z}) \subset V$. Thus, u may be considered as a meromorphic function on a (compact) torus $T = V/\mathcal{L} + \tau\mathcal{L}$, which is isomorphic to the product of n copies of the elliptic curve $\mathcal{E} = \mathbb{C}/\mathbb{Z} + \tau\mathbb{Z}$. Singularities of $u(x)$ are the second order poles along the following set of the hyperplanes:
$$Sing = \bigcup_{\alpha \in \mathcal{A}} \bigcup_{m,n \in \mathbb{Z}} \pi_\alpha^{m,n}, \qquad \pi_\alpha^{m,n} := \{x: \; \alpha(x) = m + n\tau\}.$$

We will assume that all hyperplanes $\pi_\alpha^{m,n}$ are pairwise different; this can always be achieved by rearranging the terms in (2.2). This will imply that
$$u(x) \sim c_\alpha(\alpha(x) - m - n\tau)^{-2} + O(1) \quad \text{near } \pi_\alpha^{m,n}.$$

Our next important assumption is that each c_α in (2.2) has a form
$$c_\alpha = m_\alpha(m_\alpha + 1)(\alpha_0, \alpha_0) \qquad \text{with some} \quad m_\alpha \in \mathbb{Z}_{>0}.$$

Now we are going to put some more restrictions on u demanding its quasi-invariance in the following sense.

Definition. Let us say that the potential (2.2) as above is **quasi-invariant** if for any hyperplane $\pi = \pi_\alpha^{m,n} \in Sing$ the (meromorphic) function $u(x) - u(s_\pi x)$ is divisible by $(\alpha(x) - m - n\tau)^{2m_\alpha + 1}$, where s_π denotes the orthogonal reflection with respect to π.

Here are two important examples of such potentials (more examples will appear later).

Example 2.1. Consider the following potential $u(x)$ in $\mathbb{C}^n$:
$$(2.3) \qquad u = \sum_{i<j} 2m(m+1)\wp(x_i - x_j), \quad m \in \mathbb{Z}_{>0}.$$

It is invariant under any permutation of the coordinates $x^1, \ldots, x^n$, and also under translations $x \mapsto x + l$ for $l \in \mathbb{Z}^n + \tau\mathbb{Z}^n$ ($\mathbb{Z}^n$ is the standard integer lattice in n dimensions). As a result, u will be symmetric with respect to any of the hyperplanes $x_i - x_j = m + n\tau$. Thus, its Laurent expansion in the normal direction will have no odd terms at all, hence u is quasi-invariant. The corresponding Schrödinger operator (2.1) is the Hamiltonian of the quantum elliptic Calogero–Moser problem. More generally, the elliptic Calogero–Moser problems related to other root systems [9] also lead, in the same way, to quasi-invariant potentials. In particular, for the rank-one system A_1 we have the classical Lamé operator (1.1)

Example 2.2. This example is in dimension one. The potential u has N poles $x_1, \ldots, x_N$ and looks as
$$(2.4) \qquad u = \sum_{i=1}^N 2\wp(x - x_i).$$

To ensure its quasi-invariance, one has to impose the condition that u has zero derivative at each of its poles, more explicitly:

$$(2.5) \qquad \sum_{j \neq i} \wp'(x_i - x_j) = 0 \qquad \text{for all } i = 1, \ldots, N.$$

This system of equations describes the so-called 'elliptic locus' from [24], which has an intimate connection with the classical elliptic Calogero–Moser system and the KdV hierarchy.

Let us call a Schrödinger operator L with quasi-invariant elliptic potential $u(x)$ a **generalized Lamé operator**. In trigonometric and rational versions ($\wp(x) = \sin^{-2} x$ or x^{-2}) such operators were considered in [12], where their eigenfunctions were effectively constructed. From the results of [12] the so-called algebraic integrability of L follows (see the paper [13] for the rational case). We recall the definition of the algebraic integrability in the next section, following [8, 11]; let us just remark that in dimension one this coincides with the class of algebro-geometric operators which appear in the finite-gap theory, see [2, 25]. This motivates the following

Conjecture. *The generalized Lamé operators are all algebraically integrable.*

As a particular case, this contains a conjecture of [8] about the algebraic integrability of the elliptic Calogero–Moser problems. As we already mentioned in the introduction, for the A_n-case (2.3) this has been proved by Braverman, Etingof and Gaitsgory in [11]. It is also known to be true in dimension one, due to Gesztesy and Weikard [14]. In the next section we prove this conjecture under additional assumption of the usual, Liouville integrability of L (in a slightly stronger sense). As a corollary, we will obtain the algebraic integrability of the quantum Calogero–Moser problems for integer coupling parameters.

3. Monodromy and algebraic integrability

Let L be a generalized Lamé operator as defined previously. Recall that L is **completely integrable** if it is a member of a commutative family of differential operators $L_1 = L, L_2, \ldots, L_n$ which are algebraically independent. We assume that the L_i's have meromorphic coefficients and are periodic with respect to the same lattice, which makes them (singular) differential operators on the torus $T = \mathbb{C}^n/\mathcal{L} + \tau\mathcal{L}$. The following proposition shows that possible singularities of L_i are contained in the singular locus $Sing$ of the Schrödinger operator L.

Proposition 3.1. *Let L be a Schrödinger operator regular in an open set U. Then any differential operator M on U with meromorphic coefficients commuting with L is regular in U.*

To prove the proposition, we will need the following lemma.

Lemma 3.2. *Let $S(x, p)$ be a meromorphic function on $T^*U = U \times V^*$ which is polynomial in the momentum p, and $\{p^2, S(x, p)\}$ is a regular function. Then S is a regular function.*

Proof. Assume the contrary. The function S is a finite sum $\sum S_{\mathbf{k}}(x)p^{\mathbf{k}}$, where $p^{\mathbf{k}}$ are monomials. Let $D \subset U$ be the divisor of poles of S. Take a generic point z_0 of this divisor. Near this point D is given by an equation $f = 0$, where f is analytic

at z_0 and $df(z_0) \neq 0$. Let $S = \frac{Q}{f^k}(1 + O(f))$ near z_0 (Q is regular at z_0, with $Q(z_0) \neq 0$). Then

$$\{p^2, S\} = -2k \sum p_i \frac{\partial f}{\partial x_i} f^{-k-1} Q + O(f^{-k}).$$

But $\sum p_i \frac{\partial f}{\partial x_i}(z_0, p) \neq 0$ for generic p. Thus, $\{p^2, S\}$ is singular, which is a contradiction. $\qquad\square$

Now we prove the proposition. Suppose $[M, L] = 0$. Assume M is not regular. Then we can write M as $M' + M''$, where M'' is regular, and M' has a singular highest symbol. Then $[L, M'] = -[L, M'']$ is regular. Let $S(x, p)$ be the symbol of M'. We have $\{p^2, S\}$ is regular (since if it is nonzero, it is the symbol of $[L, M']$). Then the lemma implies that S is regular. This contradiction proves the proposition.

Notice also that if $S(x, p)$ is the highest symbol of L_i, then from $[L, L_i] = 0$ it follows that $\{p^2, S\} = 0$. Thus, by Lemma 3.2, S must be regular everywhere. Hence, each L_i must have constant highest symbol, i.e. $L_i = s_i(\partial) + \ldots$ for some polynomial s_i.

Definition. Let us say that a Schrödinger operator $L = -\Delta + u$ in $V = \mathbb{C}^n$ is **strongly integrable** if the commuting operators $L_1 = L, \ldots, L_n$ have algebraically independent homogeneous constant highest symbols $s_1, \ldots, s_n$ and if $\mathbb{C}[V]$ is finitely generated as a module over the ring generated by $s_1, \ldots, s_n$ or, equivalently, if the system $s_1(\xi) = 0, \ldots, s_n(\xi) = 0$ has the unique solution $\xi = 0$.

Now let L be a strongly integrable generalised Lamé operator, so we have the operators $L_1 = L, \ldots, L_n$ with meromorphic coefficients on the torus $T = \mathbb{C}^n/\mathcal{L} + \tau\mathcal{L}$, and $L_i = s_i(\partial) + \ldots$. First of all, $\mathbb{C}[V]$ is locally free as a module over $\mathbb{C}[s_1, \ldots, s_n]$. This follows from the fact, due to Serre [26], that if $f : X \to Y$ is a finite map of smooth affine varieties of the same dimension, then $\mathcal{O}(X)$ is a locally free $\mathcal{O}(Y)$-module. Further, since s_i are homogeneous, this module is graded, hence, it must be free. Denote by N the rank of this free module.

Consider now the eigenvalue problem

(3.1) $$L_i \psi = \lambda_i \psi, \quad i = 1, \ldots, n,$$

with $\lambda = (\lambda_1, \ldots, \lambda_n) \in \mathbb{C}^n$. Then the space of solutions of this system in any simply connected domain in $T \setminus Sing$ is N-dimensional. So we have a holonomic system of rank N on T with singularities along a finite union of hypertori $Sing \subset T$.

Theorem 3.3. *The holonomic system* (3.1) *has regular singularities.*

Proof. Regularity of singularities is a codimension one condition. Thus, it is sufficient to restrict our attention to a neighborhood U of a point which lies on exactly one subtorus from the pole divisor. Let us assume that this point is 0, and the subtorus is locally defined by the equation $x_1 = 0$.

Lemma 3.4. *For any* $r \geq 0$, *the singular part of the differential operator* $(x_1)^r L_i$ *has the order at most* $d_i - r - 1$, *where* d_i *is the degree of* s_i.

Proof. Let us introduce new variables $y_j = tx_j$, and write our operators with respect to them. Then $L = t^{-2}L^{(0)} + O(1)$, $t \to 0$, where $L^{(0)} = -\Delta + \frac{m_\alpha(m_\alpha+1)}{x_1^2}$ with $m_\alpha \in \mathbb{Z}_+$ corresponding to the chosen hyperplane $x_1 = 0$. Let $L_i^{(0)}$ be the coefficient at the lowest power of t in the expression for L_i. Then $L_i^{(0)}$ is homogeneous, of

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degree $\leq -d_i$ in t (since the symbol of L_i has this degree). On the other hand, the order of this operator is at most d_i. Thus, if this degree of $L_i^{(0)}$ is less than d_i, then its symbol would have to be singular. But $L_i^{(0)}$ commutes with $L^{(0)}$, so this contradicts Lemma 3.2. Thus, the degree is exactly d_i, which implies the statement. □

Lemma 3.5. Consider a system of differential equations $df/dz = A(z)f(z)$ with holomorphic coefficients on a punctured disk $0 < |z| < \epsilon$ (f is a vector function, A is a matrix function). Assume that $A(z)$ is meromorphic at $z = 0$ and that there exists an integer-valued function $D(i)$ such that the order of $a_{ij}(z)$ at $z = 0$ is at least $D(j) - D(i) - 1$. Then the system has a regular singularity at $z = 0$.

Indeed, let us make a change of variable $g_i = z^{D(i)} f_i$. This will change the matrix A into a new matrix $\tilde{A}$ which obviously has at most simple pole at $z = 0$.

Now let us prove the theorem. First, let us reduce (3.1) to a first order holonomic system in a standard way. Choose a collection of N homogeneous polynomials $q_1, ..., q_N$ in ∂_i, which form a basis in $\mathbb{C}[\partial_1, ..., \partial_n]$ as a free module over $\mathbb{C}[s_1(\partial), ..., s_n(\partial)]$. Let ψ be a solution the eigenvalue problem (3.1), and consider the functions

$$q_1(\partial)\psi, ..., q_N(\partial)\psi \,.$$

Then, for any polynomial q of ∂_i, the function $q\psi$ can be expressed via $q_i\psi$, with the coefficients depending on x and λ. Indeed, assume that q is homogeneous of degree d. We know that q can be uniquely represented in the form $\sum g_j q_j$, where $g_j \in \mathbb{C}[s_1, ..., s_n]$. Thus, $q\psi - \sum q_j g_j(L_1, .., L_n)\psi$ is expressed through differential polynomials of ψ of degree smaller than d. But $g_j(L_1, ..., L_n)\psi = g_j(\lambda_1, ..., \lambda_n)\psi$, so, eventually, by induction we get a desired representation of $q\psi$.

Now observe that by Lemma 3.4, the coefficient of $q_j\psi$ in the expansion of $q\psi$ has a pole in x_1 of order at most $\deg(q) - \deg(q_j)$. Thus, we have a holonomic system of matrix partial differential equations

$$\partial_k q_i \psi = \sum a_{ij}^{(k)}(x) q_j \psi \quad k = 1, \ldots, n \,,$$

which is equivalent to the system (3.1). Each of the matrices $a_{ij}^{(k)}$ ($k = 1, \ldots, n$) satisfies the conditions of Lemma 3.5 with respect to $z = x_1$, for $D(i) = -\deg(q_i)$. In particular, using the lemma, we conclude from the first equation $\partial_1 q_i \psi = \sum a_{ij}^{(1)} \psi$ that all the solutions have at most power growth in x_1 when approaching $x_1 = 0$, hence the system (3.1) has a regular singularity at $x_1 = 0$. □

Now take any point $x_0 \in T \setminus Sing$ and consider the monodromy of the system (3.1) at point x_0, this gives an N-dimensional representation of the fundamental group $\pi_1(T \setminus Sing)$.

Proposition 3.6. *The monodromy group of the system* (3.1) *is commutative for any* λ.

Proof. Take a hyperplane $\pi = \pi_\alpha^{m,n} \in Sing$ and let P be a generic point of π. Changing the coordinates if necessary, we may assume that $P = (0, \ldots, 0)$ is the origin and π is given by equation $x_1 = 0$. From the regularity of singularities it follows that there exist $\gamma_1, \ldots, \gamma_r \in \mathbb{C}$ such that any solution ψ of the system (3.1)

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near $P \in \pi$ has a convergent series expansion in the subspace

$$\bigoplus_{j=1}^{r} x_1^{\gamma_j} \mathbb{C}[[x_1, \ldots, x_n]][\log(x_1)] \,.$$

Substituting such a series into the first equation $L\psi = \lambda_1 \psi$, one arrives at certain recurrence relations from which follows that (1) we have two 'leading exponents' $\gamma_1 = -m_\alpha$, $\gamma_2 = m_\alpha + 1$, both integer; (2) there will be no $\log(x_1)$ involved. The latter fact is due to the quasi-invariance of u, see [27] for the one-dimensional case and [13], section 2 for a discussion in the multivariable setting.

As a result, we see that all the solutions are single-valued near π, so the local monodromy corresponding to a loop around π is trivial. Consequently, the global monodromy group will be a homomorphic image of the commutative group $\pi_1(T)$. $\qquad\square$

Corollary 3.7. *The differential Galois group of the system* (3.1) *is commutative for any* λ.

Proof. It is known (see [28]) that for a regular holonomic system on a smooth projective variety the differential Galois group coincides with the Zariski closure of the monodromy group. In our situation the proof is simple: first, we know that all solutions of the system (3.1) are meromorphic in $\mathbb{C}^n$. Indeed, this is true outside the set of codimension 2, by the proposition above, hence it holds everywhere by Hartogs' theorem. Now let F be the field of 'elliptic functions', i.e. meromorphic functions on the torus T, and L is the solution field of (3.1) (on some simply connected domain). The monodromy gives the homomorphism

$$\pi_1(T) \mapsto Dgal(L : F)$$

of the fundamental group of the torus T into the differential Galois group. Let G be the Zariski closure of the image of this homomorphism inside $Dgal(L : F)$. By the main theorem of the differential Galois theory [29], to prove that $G = Dgal(L : F)$ it suffices to show that in the solution field any G-invariant function is actulay $Dgal$-inavriant, i.e. belongs to F. But any meromorphic G-invariant function is $\pi_1(T)$-invariant, hence elliptic. Thus, it is $Dgal$-invariant by definition.

This proves that $Dgal(L : F) = G$, and the latter is obviously commutative. $\quad\square$

Now let us remark (see [11]) that a quantum completely integrable system (QCIS) on a smooth algebraic variety X of dimension n naturally defines an embedding

$$\theta : \mathcal{O}(\Lambda) \mapsto D(X) \,,$$

where $\Lambda \simeq \mathbb{A}^n$ is an affine space and $D(X)$ denotes the ring of differential operators on X. More generally, Λ can be any affine variety with $\dim(\Lambda) = n$. Then we have an analogous eigenvalue problem $\theta(g)\psi = g(\lambda)\psi$, $\forall g \in \mathcal{O}(\Lambda)$. The dimension of the local solution space of this system at generic point of X is called the **rank** of a QCIS. Recall further, that a QCIS $S = (\Lambda, \theta)$ is **algebraically integrable** if it is dominated by another QCIS $S' = (\Lambda', \theta')$ of **rank one** (S is dominated by S' if there is a map of algebras $h : \mathcal{O}(\Lambda) \mapsto \mathcal{O}(\Lambda')$ such that $\theta = \theta' \circ h$). In our situation, this implies that apart from the operators $L_1, \ldots, L_n$, we have additional commuting operators which are not algebraic combinations of L_i (though, of course, they are algebraically dependent with L_i). In dimension $n = 1$ this is equivalent to

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saying that L is a member of a maximal commutative ring in $D(X)$ of rank one; this is known to coincide with the class of algebro-geometric operators.

Theorem 3.8. *Any generalised Lamé operator L which is strongly integrable is algebraically integrable.*

This follows immediately from the result above and the criterion from [11]. Moreover, according to [11], for generic λ the solution space is generated by the quasiperiodic solutions:

Corollary 3.9. *There exist meromorphic 1-forms ω_j on the torus T, with first order poles and depending analytically on λ, such that the functions $\psi_j = e^{\int \omega_j}$ give a basis of the solution space of (3.1) for generic λ.*

Each of these functions will be double-Bloch, in terminology of [30]:

$$(3.2) \qquad \psi_j(x + l) = e^{2\pi i \langle a_j, l \rangle} \psi_j(x), \qquad \psi_j(x + \tau l) = e^{2\pi i \langle b_j, l \rangle} \psi_j(x),$$

for appropriate $a_j, b_j \in V^*$ and for all $l \in \mathcal{L}$. Namely,

$$\langle a_j, l \rangle = \frac{1}{2\pi i} \int_z^{z+l} \omega_j \quad \text{and} \quad \langle b_j, l \rangle = \frac{1}{2\pi i} \int_z^{z+\tau l} \omega_i$$

(since ψ_j has no branching along $Sing$, these are well defined modulo $\mathbb{Z}$). In Section 5 below we explain how one can calculate these double-Bloch solutions for the generalized Lamé operators.

Remark 3.10. Our argument applies to a more general situation when one has commuting operators $L_1, \ldots, L_n$ on an abelian variety, such that the system $L_i \psi = \lambda_i \psi$, $i = 1, \ldots, n$, is regular holonomic. Then the triviality of its local monodromy around singularities implies that this system is algebraically integrable.

4. Examples

4.1. **One-dimensional case.** Let L be a one-dimensional Schrödinger operator $L = -\frac{d^2}{dx^2} + u(x)$, $x \in \mathbb{C}$. Consider the eigenvalue problem $L\psi = \lambda\psi$. Now, assuming that u is meromorphic and has a pole at $x = 0$, let us consider the local monodromy of the solutions of this second order differential equation. Suppose that this monodromy is trivial *for all* λ, in other words, all the solutions are meromorphic at $x = 0$. Then, using the classical Frobenius analysis, one can see that u must have a pole of the second order, with no residue: $u = m(m + 1)x^{-2} + O(1)$, with integer m. Furthermore, in the series for u at $x = 0$ there must be no terms of order $2j - 1$ for all $j = 1, \ldots, m$ (see [27]). This is exactly the quasi-invariance of u with respect to the symmetry $x \to -x$.

Now let u be elliptic, with periods $1, \tau$. Let us demand all the solutions of the equation $L\psi = \lambda\psi$ to be meromorphic in $\mathbb{C}$ (such u are called Picard potentials in [25, 14]). By the discussion above, this is equivalent to the quasi-invariance of u at each pole. More explicitly,

$$u(x) = \sum_{i=1}^{M} m_i(m_i + 1)\wp(x - x_i), \quad \text{with} \quad m_i \in \mathbb{Z}_+,$$

and the poles x_i must satisfy the following system of equations, which generalizes (2.5):

$$(4.1) \qquad \sum_{j \neq i} m_j(m_j + 1)\wp^{(2s-1)}(x_i - x_j) = 0$$

for all $i = 1, \ldots, M$ and $s = 1, \ldots, m_i$.

Such L automatically defines a $QCIS$ (of rank 2), and the regularity of singularities is obvious. Applying the results of the previous section, we conclude that L is algebraically integrable. Algebraic integrability of L implies the existence of a differential operator P, commuting with L. Since P is not a polynomial of L, we may assume that it is of odd order. Thus, L must be algebro-geometric, according to the Burchnall–Chaundy–Krichever theory, see e.g.[31]. Thus, our result in this case is equivalent to the main result of [14]. Notice that our approach easily extends to the case of operators of any order (cf. the remark at the end of [14]).

4.2. **Quantum Calogero–Moser system.** Let V be a complex Euclidean space, $\dim V = n$. Let $R = \{\alpha\}$ be a reduced irreducible root system in V^*, W be the corresponding Weyl group, and the parameters m_α be chosen in a W-invariant way. The corresponding Calogero–Moser operator [9] looks as

$$(4.2) \qquad L = -\Delta + \sum_{\alpha \in R_+} m_\alpha(m_\alpha + 1)(\alpha, \alpha)\wp(\langle \alpha, x \rangle).$$

Let $\mathbb{C}[V]^W$ be the ring of W-invariant polynomials. By the Chevalley theorem, it is freely generated by n elements $p_1, \ldots, p_n$, and $\mathbb{C}[V]$ is a free module over $\mathbb{C}[V]^W$, of rank $|W|$. The following result has been proved in [15] for any W-invariant $m_\alpha \in \mathbb{C}$.

Theorem 4.1 (Cherednik). *For each homogenious $p \in \mathbb{C}[V]^W$ there exists a differential operator L_p with the highest symbol p, commuting with L: $[L, L_p] = 0$. The family $\{L_p\}$ is commutative.*

For integer m_α the potential u in (4.2) is quasi-invariant (cf. Example 2.1). Altogether this proves the conjecture of [8]:

Corollary 4.2. *The Calogero–Moser operator (4.2) is algebraically integrable for integer m_α.*

Let us mention that for the classical root systems $R = A \ldots D$ the complete set of commuting operators $L_1, \ldots, L_n$ for (4.2) was explicitly found by Ochima and Sekiguchi [34]. Their results cover the BC_n case, too. In that case we have 5 parameters m, g_0, g_1, g_2, g_3 and the Inozemtsev operator

$$(4.3) \quad L = -\Delta + 2m(m+1)\sum_{i<j}(\wp(x_i-x_j)+\wp(x_i+x_j)) + \sum_{i=1}^{n}\sum_{s=0}^{3} g_s(g_s+1)\wp(x_i+\omega_s),$$

with $\omega_s(s = 0 \ldots 3)$ denoting the half-periods $0, 1/2, \tau/2, (1+\tau)/2$. The Weyl group W for this case is generated by the permutations of x_i and sign flips, and Theorem 4.1 still holds true, due to [34]. Applying Theorem 3.8 we obtain

Corollary 4.3. *The Inozemtsev operator (4.3) is algebraically integrable for any integer m, g_0, g_1, g_2, g_3.*

4.3. Deformed root systems. Other known examples of the generalized Lamé operators in dimension > 1 are related to deformed root systems, which appeared in [13]. Below we describe the set of linear functionals $\mathcal{A} = \{\alpha\}$ and the corresponding multiplicities m_α.

(1) $A_{n,1}(m)$ system [13].
It consists of the following covectors in $\mathbb{C}^{n+1}$:

$$\begin{cases} x_i - x_j, & 1 \leq i < j \leq n, \quad \text{with multiplicity } \langle m \rangle, \\ x_i - \sqrt{m}x_{n+1}, & i = 1, \ldots, n \quad \text{with multiplicity } 1. \end{cases}$$

Here m is an integer parameter, and $\langle m \rangle$ stands for $\langle m \rangle = \max\{m, -1 - m\}$.

(2) $C_{n,1}(m, l)$ system [13].
It consists of the following covectors in $\mathbb{C}^{n+1}$:

$$\begin{cases} x_i \pm x_j, & 1 \leq i < j \leq n, \quad \text{with multiplicity } \langle k \rangle, \\ 2x_i, & i = 1, \ldots, n \quad \text{with multiplicity } \langle m \rangle, \\ x_i \pm \sqrt{k}x_{n+1}, & i = 1, \ldots, n \quad \text{with multiplicity } 1, \\ 2\sqrt{k}x_{n+1} & \text{with multiplicity } \langle l \rangle. \end{cases}$$

Here k, l, m are integer parameters related as $k = \frac{2m+1}{2l+1}$, and $\langle k \rangle, \langle l \rangle, \langle m \rangle$ have the same meaning as in $A_{n,1}(m)$ case. In two-dimensional case $n = 1$ the first group of roots is absent and there is no restriction for k to be integer.

(3) Here is a BC_n-type generalization of the previous example. Let $\omega_s (s = 0 \ldots 3)$ denote the half-periods, as in BC_n case (4.3). The set of linear functionals $\alpha \in \mathcal{A}$ and the corresponding multiplicities look as follows:

$$\begin{cases} x_i \pm x_j, & 1 \leq i < j \leq n, \quad \text{with multiplicity } \langle k \rangle, \\ x_i + \omega_s, & i = 1, \ldots, n \quad \text{with multiplicity } \langle m_s \rangle, (s = 0 \ldots 3), \\ x_i \pm \sqrt{k}x_{n+1}, & i = 1, \ldots, n \quad \text{with multiplicity } 1, \\ \sqrt{k}x_{n+1} + \omega_s & \text{with multiplicity } \langle l_s \rangle, (s = 0 \ldots 3). \end{cases}$$

Here k, l_s, m_s are nine integer parameters related through $k = \frac{2m_s+1}{2l_s+1}$ for all $s = 0 \ldots 3$. The previous case corresponds to $m_s \equiv m$ and $l_s \equiv l$. Again, in case $n = 1$ the first group of roots is absent and k may not be integer.

(4) Hietarinta operator [19].
In this case we have three covectors in $\mathbb{C}^3$,

$$\alpha = a_1 x_1 - a_2 x_2, \beta = a_2 x_2 - a_3 x_3, \gamma = a_1 x_1 - a_3 x_3,$$

with $m_\alpha = m_\beta = m_\gamma = 1$. Here a_i are arbitrary complex parameters such that $a_1^2 + a_2^2 + a_3^2 = 0$. Notice that the system is essentially two-dimensional since $\alpha + \beta + \gamma = 0$.

(5) $A_{n-1,2}(m)$ system [16].
It consists of the following covectors in $\mathbb{C}^{n+2}$:

$$\begin{cases} x_i - x_j, & 1 \leq i < j \leq n, \quad \text{with multiplicity } m, \\ x_i - \sqrt{m}x_{n+1}, & i = 1, \ldots, n \quad \text{with multiplicity } 1, \\ x_i - \sqrt{-1 - m}x_{n+2}, & i = 1, \ldots, n \quad \text{with multiplicity } 1, \\ \sqrt{m}x_{n+1} - \sqrt{-1 - m}x_{n+2} & \text{with multiplicity } 1. \end{cases}$$

Notice that for $m = 1$ this system coincides with the system $A_{n,1}(-2)$ above.

In all these cases a direct check shows that the corresponding potential u is quasi-invariant. Notice that in all cases u is symmetric with respect to s_α as soon as $m_\alpha > 1$. Thus, one have to check the quasi-invariance only for those α where $m_\alpha = 1$.

We believe that all these operators are algebraically integrable. In the next section we check this for all two-dimensional examples.

4.4. **Two-dimensional case.** Let us check that all known two-dimensional generalized Lamé operators are algebraically integrable. Apart from the root systems A_2, BC_2 and G_2 considered previously, we have three deformed cases, namely, the $A_{1,1}(m)$ case, the Hietarinta operator and the deformed BC_2 case.

First, let us consider the $A_{1,1}(m)$ case:

$$(4.4) \quad L = -\partial_1^2 - \partial_2^2 - \partial_3^2 + 2m(m+1)\wp(x_1 - x_2) +$$
$$2(m+1)\wp(x_1 - \sqrt{m}x_3) + 2(m+1)\wp(x_2 - \sqrt{m}x_3).$$

In this case we can use the result of [32] where the complete integrability of (4.4) was established. First, L obviously commutes with $L_0 = \partial_1 + \partial_2 + \frac{1}{\sqrt{m}}\partial_3$.

Proposition 4.4 ([32]). *For any m there exists a third order operator L_2 commuting with L_0, L, and its highest symbol is $\partial_1^3 + \partial_2^3 + \sqrt{m}\partial_3^3$.*

It is easy to check that as soon as $m \neq -1$, the highest symbols of L_0, L, L_2 will satisfy the requirements of the strong integrabilty (notice that for $m = -1$ the operator L is trivial). As a result, for integer m we obtain the algebraic integrability of the operator (4.4). Note that for the special case $m = 2$ the algebraic integrability of (4.4) was demonstrated in [33] by presenting an explicit extra operator commuting with L_0, L, L_2.

Now let us consider the Hietarinta operator

$$(4.5) \quad L = -\partial_1^2 - \partial_2^2 - \partial_3^2 + 2(a_1^2 + a_2^2)\wp(a_1 x_1 - a_2 x_2) +$$
$$2(a_2^2 + a_3^3)\wp(a_2 x_2 - a_3 x_3) + 2(a_3^2 + a_1^2)\wp(a_3 x_3 - a_1 x_1),$$

where $a_1^2 + a_2^2 + a_3^2 = 0$. Such L commutes with $L_0 = a_1^{-1}\partial_1 + a_2^{-1}\partial_2 + a_3^{-1}\partial_3$, and we need one more operator for the complete integrability (we assume that all a_i are nonzero, otherwise L is reducible). Such operator was found in [19].

Proposition 4.5 ([19]). *There exists a third order operator L_2 commuting with L_0, L above, and its highest symbol is $a_1\partial_1^3 + a_2\partial_2^3 + a_3\partial_3^3$.*

If we denote the highest symbols of these three operators as s_1, s_2, s_3, then it is easy to check that the system $s_1(\xi) = s_2(\xi) = s_3(\xi) = 0$ has the only solution $\xi = 0$; the only exception is the case when $a_1^3 = a_2^3 = a_3^3$. As a result, we conclude that for all values of the parameters (apart from the case $a_1^3 = a_2^3 = a_3^3$) the Hietarinta operator is strongly integrable, thus, it is algebraically integrable. Note that this also follows from [19] where one more operator commuting with L_0, L, L_2 was found.

Remark 4.6. In the case $a_1^3 = a_2^3 = a_3^3$ the operator (4.5) is still algebraically integrable, although it is no longer strongly integrable.

Finally, let us consider the deformed BC_2 case. The Schrödinger operator L has the following form:

$$(4.6) \qquad\qquad L = -\partial_x^2 - \partial_y^2 + U(x, y),$$

where $U = 2(k+1)(\wp(x + \sqrt{k}y) + \wp(x - \sqrt{k}y)) + v(x) + w(y)$ and v, w are given by the expressions

$$(4.7) \qquad v = \sum_s m_s(m_s + 1)\wp(x + \omega_s)\,, \quad w = k\sum_s l_s(l_s + 1)\wp(\sqrt{k}y + \omega_s)\,.$$

Here $\omega_0, \omega_1, \omega_2, \omega_3$ are the half-periods and m_s, l_s and k are nine parameters such that $k = (2m_s + 1)/(2l_s + 1)$ for all $s = 0, 1, 2, 3$ (thus, effectively, L contains five independent parameters).

Proposition 4.7. *For any values of the parameters m_s, l_s, k such that $k = \frac{2m_s+1}{2l_s+1}$ the following operator commutes with L:*

$$\begin{aligned}
M = &- \partial_x^4 - k\partial_y^4 + 2(U - w)\partial_x^2 - 4\sqrt{k}(k+1)(\wp(x + \sqrt{k}y) - \wp(x - \sqrt{k}y))\partial_x\partial_y + \\
&2k(U - v)\partial_y^2 + (2v' + 2(k+1)(2-k)(\wp'(x + \sqrt{k}y) + \wp'(x - \sqrt{k}y)))\partial_x + \\
&(2k^2w' + 2\sqrt{k}(k+1)(2k-1)(\wp'(x - \sqrt{k}y) - \wp'(x + \sqrt{k}y)))\partial_y - \\
&(k+1)^3\wp(x + \sqrt{k}y)\wp(x - \sqrt{k}y) + 8(k^3 + 1)(\wp^2(x + \sqrt{k}y) + \wp^2(x - \sqrt{k}y)) - \\
&4(k+1)(v + kw)(\wp(x + \sqrt{k}y) + \wp(x - \sqrt{k}y)) + v'' - v^2 + k(w'' - w^2)\,.
\end{aligned}$$

Here v', w' and so on are the derivatives with respect to the corresponding variable.

Now since the system $\xi_1^2 + \xi_2^2 = \xi_1^4 + k\xi_2^4 = 0$ does not have nontrivial solutions as soon as $k \neq -1$, we conclude that L is strongly integrable (for $k = -1$ this is also true because L is reducible in that case). Hence, for any integer values of the parameters l_s, m_s the operator (4.6)–(4.7) is algebraically integrable.

5. Bloch solutions

Let L be a generalized Lamé operator which is strongly integrable, thus algebraically integrable. We know already that for generic λ the solution space of (3.1) is spanned by the meromorphic double-Bloch solutions. Now we are going to explain how one can, in principle, calculate them.

Let $\mathcal{W}$ denote the following linear subspace in the space of meromorphic functions on $\mathbb{C}^n$. First, its elements are holomorphic everywhere apart from the singular locus $Sing = \bigcup \pi_\alpha^{m,n}$ of the operator L, where they may have poles, of order $\leq m_\alpha$ along $\pi_\alpha^{m,n}$. Next, take any hyperplane $\pi = \pi_\alpha^{m,n}$ with s_π denoting the orthogonal reflection with respect to π. Then any function $\varphi \in \mathcal{W}$ must have the following property:

$$(5.1) \qquad \varphi(x) - (-1)^{m_\alpha}\varphi(s_\pi x) \text{ is divisible by } (\alpha(x) - m - n\tau)^{m_\alpha + 1}\,.$$

Proposition 5.1. *The subspace $\mathcal{W}$ is stable under the action of L: $L(\mathcal{W}) \subseteq \mathcal{W}$. Furthermore, any meromorphic eigenfunction φ of L must belong to $\mathcal{W}$. The same is true for any of the commuting operators $L_2, \ldots, L_n$: $L_i(\mathcal{W}) \subseteq \mathcal{W}$.*

Proof. Consider any hyperplane $\pi \in Sing$ and adjust the coordinates in such a way that π is given by equation $x_n = 0$. Take a generic point in π and expand φ in Laurent series in normal direction to π, i.e. $\varphi = \sum_{j\in\mathbb{Z}} a_j(x_n)^j$, $a_j = a_j(x_1, \ldots, x_{n-1})$. Now put

$$M := \{-m_\alpha + 2\mathbb{Z}_{\geq 0}\} \cup \{m_\alpha + 1 + 2\mathbb{Z}_{\geq 0}\}$$

and split the series into two parts, with $j \in M$ and with $j \in \mathbb{Z}\backslash M$: $\varphi = \varphi_1 + \varphi_2$. First claim is that an application of L to φ_1 will produce a series of a similar kind.

This follows directly from the quasi-invariance of u, proving the first part of the proposition. On the other hand, if $a_j(x_n)^j$ is the first nonzero term in φ_2, then applying L to ψ_2 will give a series starting from $(x_n)^{j-2}$, which would contradict the equation $L\varphi = \lambda\varphi$, thus proving the second claim.

In a similar way, if $L'L = LL'$ for some other operator L', then $L'(L)^r = (L)^r L'$ for any $r \geq 1$. Thus, if $\mathcal{W}' := L'(\mathcal{W})$ then $L^r(\mathcal{W}') \subseteq \mathcal{W}'$ for any r. Now suppose we could find a function φ in $\mathcal{W}'$ which is not in $\mathcal{W}$. Then, consider a series expansion of φ in the direction, normal to π, and split it into $\varphi = \varphi_1 + \varphi_2$ as above. If $\varphi_2 \neq 0$, then $L^r\varphi$ would have a pole of an arbitrarily high order along π (as r increases), which is impossible for an element in $\mathcal{W}'$ (since $\mathcal{W}' = L'\mathcal{W}$ and L' has meromorphic coefficients). This would contradict the inclusion $L^r(\mathcal{W}') \subseteq \mathcal{W}'$. Thus, $\mathcal{W}' = \mathcal{W}$. $\qquad\square$

Now let ψ be a double-Bloch solution of (3.1), so for appropriate $a, b \in V^*$ and for any $l \in \mathcal{L}$ we have:

$$(5.2) \qquad \psi(x + l) = \psi(x)e^{2\pi i\langle a,l\rangle}, \quad \psi(x + \tau l) = \psi(x)e^{2\pi i\langle b,l\rangle}.$$

We know that ψ is meromorphic in $\mathbb{C}^n$ with possible poles along the hyperplanes $\pi_\alpha^{m,n}$, of order m_α. In our discussion below we restrict ourselves to the case when all the linear functions $\alpha \in \mathcal{A}$ have zero constant term, i.e. $\alpha = \alpha_0 \in V^*$ for all α, so $\alpha(x) = \langle\alpha, x\rangle$. Everything extends to the general case with obvious modifications.

As a result, we see that ψ can be presented in the form

$$(5.3) \qquad \psi = \Phi/\delta, \qquad \delta(x) = \prod_{\alpha\in\mathcal{A}} \theta(\langle\alpha, x\rangle)^{m_\alpha},$$

for some holomorphic $\Phi(x)$. Here $\theta = \theta_1$ is the classical (odd) Jacobi theta function,

$$(5.4) \qquad \theta(z) = \sum_{n\in\mathbb{Z}} \exp(\pi i(n + 1/2)^2\tau + 2\pi i(n + 1/2)(z + 1/2)).$$

Recall that $\theta(z)$ has the following translation properties in z:

$$\theta(z + 1) = -\theta(z), \qquad \theta(z + \tau) = -e^{-2\pi i z - \pi i\tau}\theta(z).$$

This determines the translation properties of δ. To write them down, it is convenient to introduce the following linear map $\Omega : V \to V^*$ which is defined as

$$(5.5) \qquad \Omega : x \mapsto \sum_{\alpha\in\mathcal{A}} m_\alpha\langle\alpha, x\rangle\alpha.$$

Note that Ω maps the lattice $\mathcal{L}$ to a sublattice in $\mathcal{M} = \mathrm{Hom}(\mathcal{L}, \mathbb{Z})$. We also need a covector $\varrho = \frac{1}{2}\sum_{\alpha\in\mathcal{A}} m_\alpha\alpha$.

Under these notations, we have the following translation formulas for any $l \in \mathcal{L}$:

$$(5.6) \qquad \delta(x + l) = e^{2\pi i\langle\varrho,l\rangle}\delta(x),$$

$$(5.7) \qquad \delta(x + l\tau) = e^{2\pi i\langle\varrho,l\rangle - 2\pi i\langle\Omega l,x\rangle - \pi i\langle\Omega l,l\rangle\tau}\delta(x).$$

As a corollary of (5.2) and (5.6)-(5.7), we conclude that the numerator Φ in (5.3) must have the translation properties as follows:

$$\Phi(x + l) = e^{2\pi i\langle a+\varrho,l\rangle}\Phi(x),$$

$$\Phi(x + l\tau) = e^{2\pi i\langle b+\varrho,l\rangle - 2\pi i\langle\Omega l,x\rangle - \pi i\langle\Omega l,l\rangle\tau}\Phi(x).$$

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The vector space of entire functions with such properties is finite-dimensional. Indeed, let $\omega(x,y)$ denote the bilinear form on V associated with the operator Ω:

$$(5.8) \qquad \omega(x,y) = \sum_{\alpha \in \mathcal{A}} m_\alpha \langle \alpha, x \rangle \langle \alpha, y \rangle \,.$$

It is symmetric positive and integer-valued on the lattice $\mathcal{L}$. Let us define $\Theta\begin{bmatrix} p \\ q \end{bmatrix}$ by the following series:

$$(5.9) \qquad \Theta\begin{bmatrix} p \\ q \end{bmatrix}(x) = \sum_{l \in \mathcal{L}} \exp(2\pi i \omega(l+p, x+q) + \pi i \tau \omega(l+p, l+p)) \,.$$

It has the following translation properties:

$$(5.10) \qquad \Theta\begin{bmatrix} p \\ q \end{bmatrix}(x+l) = e^{2\pi i \omega(l,p)} \Theta\begin{bmatrix} p \\ q \end{bmatrix}(x) \,,$$

$$(5.11) \qquad \Theta\begin{bmatrix} p \\ q \end{bmatrix}(x+l\tau) = e^{-2\pi i \omega(l,x+q) - \pi i \tau \omega(l,l)} \Theta\begin{bmatrix} p \\ q \end{bmatrix}(x) \,.$$

It is easy to show (see e.g.[35]) that the space of holomorphic functions with such translation properties has dimension equal to $[\mathcal{M} : \Omega\mathcal{L}]$; this is equal to $\det(\Omega_{ij})$ where $\Omega_{ij} = \langle \Omega e_i, e_j \rangle$ for some basis $e_1, \ldots, e_n$ of $\mathcal{L}$. A natural basis in this space is given by the functions $\Theta\begin{bmatrix} p \\ q+r \end{bmatrix}$ with $r \in \Omega^{-1}\mathcal{M}$ running over the set of representatives in $\Omega^{-1}(\mathcal{M})/\mathcal{L}$.

For the later purposes, let us use slightly different basis, namely, the functions

$$(5.12) \qquad \Phi_r = e^{\langle k, x \rangle} \Theta(x + \gamma + r) \,, \qquad \Theta := \Theta\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad r \in \Omega^{-1}(\mathcal{M})/\mathcal{L} \,.$$

It is easy to relate the parameters $k \in V^*$ and $\gamma \in V$ to p, q:

$$k = 2\pi i \Omega p \,, \qquad \gamma = q + \tau p \,.$$

Let us denote the linear space generated by the functions (5.12) as $\mathcal{U}_{k,\gamma}$.

We conclude that ψ must belong to linear space $\delta^{-1}\mathcal{U}_{k,\gamma}$ with k, γ related in a simple way to the 'quasimomenta' a, b in (5.2). Now recall Proposition 5.1. It implies that ψ must belong to the (finite-dimensional) subspace $\mathcal{W}_{k,\gamma} = \left(\delta^{-1}\mathcal{U}_{k,\gamma} \right) \cap \mathcal{W}$. It also implies that L (as well as any of L_i's) preserves this finite-dimensional space, so we can eventually find ψ by diagonalizing the action of L on $\mathcal{W}_{k,\gamma}$. Note that since the double-Bloch solutions ψ form an n-parametric family (with $\lambda = (\lambda_1, \ldots, \lambda_n)$ being the parameters), this space $\mathcal{W}_{k,\gamma}$ will be nonzero only for (k, γ) belonging to a certain n-dimensional subvariety. In most cases $\dim \mathcal{W}_{k,\gamma} \leq 1$, so the (unique) function $\psi_{k,\gamma}$ generating $W_{k,\gamma} \neq 0$ will be an eigenfunction for L automatically.

All this simplifies a little for the Calogero–Moser models, so let us consider this case in more detail. For a given reduced, irreducible root system R in V^* and a fixed W-invariant $m(\alpha)$, we consider the Calogero–Moser operator

$$(5.13) \qquad L = -\Delta + \sum_{\alpha \in R_+} m_\alpha (m_\alpha + 1)(\alpha, \alpha) \wp(\langle \alpha, x \rangle | \tau) \,.$$

The Bloch solutions must be of the form $\psi = \delta^{-1}\Phi$ as in (5.3). Note that δ in this case has the following symmetry:

$$(5.14) \qquad \delta(wx) = \varepsilon_m(w)\delta(x) \quad \text{for any } w \in W \,,$$

where ε_m is the one-dimensional character of W such that

(5.15) $$\varepsilon_m(s_\alpha) = (-1)^{m_\alpha}.$$

The bilinear symmetric form (5.8) is obviously W-invariant, and since R is irreducible, ω must be proportional to the W-invariant scalar product (x, y). So, $\omega(x, y) = \kappa \cdot (x, y)$ for some κ which depends on m_α. (For instance, if R consists of one W-orbit only and $m_\alpha \equiv m$, one has $\omega(x, y) = mh(x|y)$ where $h = h(R)$ is the Coxeter number and the form $(x|y)$ on V is normalized in such a way that $(\alpha^\vee|\alpha^\vee) = 2$ for all $\alpha^\vee \in R^\vee$.)

The lattice $\mathcal{L}$ in this case is the coweight lattice $P^\vee$ of R, while $\mathcal{M}$ is the root lattice Q. Still, the numerator Φ must belong to the finite-dimensional space $\mathcal{U}_{k,\gamma}$ spanned by the functions (5.12).

We already know that a Bloch solution $\psi = \delta^{-1}\Phi$ appears only for those k, γ when $\delta^{-1}\mathcal{U}_{k,\gamma} \cap \mathcal{W} \neq 0$. Such k, γ can be effectively determined. Indeed, due to (5.14), the conditions (5.1) for ψ reduce to the quasi-invariance of Φ:

(5.16) $\qquad \Phi(x) - \Phi(s_\alpha x)$ is divisible by $\langle \alpha, x \rangle^{2m_\alpha+1}$ for all $\alpha \in R$.

(These are local conditions near $\pi_\alpha = \{x : \langle \alpha, x \rangle = 0\}$, similar conditions for other hyperplanes $\pi_\alpha^{m,n} \in Sing$ will follow because ψ is quasiperiodic.)

These conditions can be rewritten as

(5.17) $\qquad \langle \alpha^\vee, \partial \rangle^{2j-1} \Phi \equiv 0 \qquad$ for $\langle \alpha, x \rangle = 0$ and $j = 1, \ldots, m_\alpha$,

with $\langle \alpha^\vee, \partial \rangle$ denoting the derivative in $\alpha^\vee$-direction.

Now recall that we have the period lattice $\mathcal{L} = P^\vee$, and Φ belongs to the linear space $\mathcal{U}_{k,\gamma}$ of the functions with the translation properties (5.10)–(5.11). Consider the following sublattice $\mathcal{L}^\alpha \subseteq \mathcal{L}$:

(5.18) $\qquad \mathcal{L}^\alpha := \mathcal{L}' \oplus \mathcal{L}'', \qquad \mathcal{L}' = \mathcal{L} \cap \ker \alpha, \quad \mathcal{L}'' = \mathcal{L} \cap \mathbb{R}\alpha^\vee.$

Let $\mathcal{U}_{k,\gamma}^\alpha$ denote the space of theta functions with the same translation properties, but for the translations l from $\mathcal{L}^\alpha$ only. Obviously, we have a natural inclusion map $\mathcal{U}_{k,\gamma} \hookrightarrow \mathcal{U}_{k,\gamma}^\alpha$. It is possible to describe this linear map explicitly, using the standard bases in both spaces (look at the formula (6.4) below which is a particular example of such relation). According to (5.18), the lattice $\mathcal{L}^\alpha$ is the direct orthogonal sum of two sublattices. Thus, the corresponding theta functions from $\mathcal{U}_{k,\gamma}^\alpha$ will be the products of the $(n-1)$-dimensional theta functions related to $\mathcal{L}'$ and the one-dimensional theta functions related to the lattice $\mathcal{L}''$. This corresponds to the decomposition of $\mathcal{U}_{k,\gamma}^\alpha$ into a tensor product: $\mathcal{U}_{k,\gamma}^\alpha = (\mathcal{U}_{k,\gamma}^\alpha)' \otimes (\mathcal{U}_{k,\gamma}^\alpha)''$. Applying derivative in $\alpha^\vee$ direction will affect the one-dimensional theta functions only. As a result, for each j we have an explicit linear map $\Gamma^{\alpha,j}$ from $\mathcal{U}_{k,\gamma}$ to $(\mathcal{U}_{k,\gamma}^\alpha)'$ given by

$$\Gamma^{\alpha,j}\varphi = \langle \alpha^\vee, \partial \rangle^{2j-1}\varphi|_{\langle \alpha, x \rangle = 0}.$$

This map is given by a matrix whose entries are certain combinations of one-dimensional theta-functions and their derivatives. Now we can organize all these maps for $\alpha \in R_+$ into one big linear map

(5.19) $\qquad \Gamma : \mathcal{U}_{k,\gamma} \mapsto \bigoplus_{\substack{\alpha \in R_+ \\ j=1\ldots m_\alpha}} (\mathcal{U}_{k,\gamma}^\alpha)', \qquad \Gamma = (\Gamma^{\alpha,j})_{\alpha \in R_+, j=1,\ldots,m_\alpha},$

with $\Gamma^{\alpha,j}$ defined above. We can think of Γ as an $M \times N$ matrix, where N, M are the dimensions of the source and the target spaces, respectively.

The outcome is the following: a double-Bloch solution ψ appears exactly for those k, γ where this linear map has nontrivial kernel. This gives equations on such k, γ (by equating to zero all $N \times N$ minors of the matrix Γ). In its turn, the kernel will determine a corresponding Bloch eigenfunction. (If the kernel has dimension > 1, it still defines an invariant subspace for the action of L, so we have at least one double-Bloch solution.)

So, let $\widetilde{\mathcal{C}}$ denote an analytic subvariety in $V^* \times V$ given by

$$(5.20) \qquad\qquad \widetilde{\mathcal{C}} = \{(k, \gamma) | \ \ker \Gamma \neq 0\} \,.$$

Formulas (5.10)-(5.12) make clear that $\widetilde{\mathcal{C}}$ is invariant under the following transformations of k, γ:

$$(5.21) \qquad\qquad (k, \gamma) \mapsto (k, \gamma + l) \,, \quad l \in \Omega^{-1} \mathcal{M} \,,$$

$$(5.22) \qquad\qquad (k, \gamma) \mapsto (k + 2\pi i \Omega l, \gamma + \tau l) \,, \quad l \in \Omega^{-1} \mathcal{M} \,.$$

Now, for a function of one variable $f(z) = e^{kz} \theta(z + c)$ its derivatives at $z = 0$ are obviously polynomial in k. Therefore $\widetilde{\mathcal{C}}$, after being factored by the translations above, can be considered as an algebraic covering of an abelian variety (a product of elliptic curves) $\mathbb{C}^n / \mathcal{L}' + \tau \mathcal{L}'$ where $\mathcal{L}' = \Omega^{-1} \mathcal{M}$.

Proposition 5.2. *The double-Bloch eigenfunctions of the Calogero–Moser operator (5.13) are parametrized by the points of an algebraic variety which is a covering of an abelian variety $\mathbb{C}^n / \mathcal{L}' + \tau \mathcal{L}'$ where $\mathcal{L}' = \Omega^{-1} Q$, Q is the root lattice and the map Ω is defined by (5.5).*

A similar analysis applies to any (integrable) generalized Lamé operator, so the double-Bloch eigenfunctions are also parametrized by the points of an algebraic variety covering a product of elliptic curves.

Now let $\mathcal{C}$ denote the result of factoring the variety (5.20) by the translations (5.21)–(5.22). It is an algebraic variety parametrizing the double-Bloch eigenfunctions of L. Below, following [18], we will refer to it as the **Hermite–Bloch variety** for L. It differs from the complex Bloch variety, traditionally defined as the set of $(\mu, E) \in (\mathbb{C}^\times)^n \times \mathbb{C}$ such that there exists ψ with $L\psi = E\psi$ and $\psi(x + l_i) = \mu_i \psi(x)$ where $l_1, \ldots l_n$ is a basis in $\mathcal{L}$. Note that the latter is a transcendental complex analytic variety.

Remark 5.3. In case of the Calogero–Moser operator related to a root system R, there is a natural action of the Weyl group W on the Hermite–Bloch variety $\mathcal{C}$. Also, there is a natural projection of $\mathcal{C}$ onto $\mathbb{C}^n$ sending $\psi = \psi_{k,\gamma}$ to the set of eigenvalues λ_i, $L_i \psi = \lambda_i \psi$. This is a $|W|$-sheeted covering and the Weyl group acts on $\mathcal{C}$ by permuting the points in the fiber.

Remark 5.4. Note that our results do not contradict the theorem of Feldman–Knörrer–Trubowitz [36] in dimension two, since their result only applies to a *real-valued smooth* potential u in $\mathbb{R}^2$.

The Hermite–Bloch variety $\mathcal{C}$ is a subvariety in the total space of a certain bundle over the product of elliptic curves defined by (5.21)–(5.22). This bundle naturally compactifies to a bundle with the fibers isomorphic to the projective space $\mathbb{P}^n$. As a result, $\mathcal{C}$ compactifies to a projective variety, covering the product of elliptic curves.

The variety $\mathcal{C}$ is closely related to the so-called **spectral variety** which is defined as follows. Suppose L is a strongly integrable generalized Lamé operator, so we have n commuting operators $L_1 = L, \ldots, L_n$, which generate a commutative subalgebra in the ring of PDO with meromorphic elliptic coefficients. Then by [11], theorem 2.2, the centralizer of this subalgebra will be a maximal commutative ring which we will denote by $\mathcal{Z}(L)$ (using Proposition 5.1 one can show that the operators in this ring will share a common family of the double-Bloch eigenfunctions). Each operator in $\mathcal{Z}(L)$ must have constant highest symbols, by Lemma 3.2. Then from the strong integrability we immediately derive that $\mathcal{Z}(L)$ is finitely generated. Thus, $\mathrm{Spec}\,\mathcal{Z}(L)$ defines an affine algebraic variety, which we call the spectral variety. It is not quite clear whether the spectral variety is isomorphic to the Hermite–Bloch variety (for instance, the latter may not be affine), but at least they must be birationally equivalent.

Finally, let us remark on some algebraic geometry behind the double-Bloch solutions and the Hermite–Bloch variety for the Calogero–Moser system (5.13). We consider the torus $T = \mathbb{C}^n/Q^\vee + \tau Q^\vee$ where $Q^\vee = R^\vee \otimes \mathbb{Z}$ is the coroot lattice. Let us define the following subsheaf $\mathcal{Q} \subset \mathcal{O}(T)$ of the structure sheaf of T by requiring its local sections to have zero normal derivatives of order $1, 3, \ldots, 2m_\alpha - 1$ along each of the hyperplanes $\langle \alpha, x \rangle = 0$ (considered as hypertori in T). The sheaf $\mathcal{Q}$ can be considered as the structure sheaf $\mathcal{O}(X)$ of a singular variety X, with T being its injective normalization (cf. [39]). Such X is projective; it is a $|W|$-sheeted covering of the weighted projective space T/W considered by Looijenga [37], see also [38]. Notice that from the results of [40] it follows that X is Cohen-Macaulay and Gorenstein. Let us consider now the group $\mathrm{Pic}(X)$ of invertible sheaves on X. Then each of the double-Bloch solutions $\psi_{k,\gamma}$ represents a meromorphic section of a degree zero line bundle on X (to define degree, we use the pull-back to the torus T). In this way the Hermite–Bloch variety for the Calogero–Moser system becomes an n-dimensional subvariety in $\mathrm{Pic}^0(X)$. It would be interesting to study this relation in more detail.

Remark 5.5. An interesting thing is to analyse how the spectral variety changes when τ goes to $+i\infty$ (trigonometric limit). In this limit the spectral variety becomes rational and is relatively well understood. Thus, one could think of the whole family depending on τ as a deformation of this rational variety. This point of view was used in [41] to construct the spectral surface in the simplest A_2 case.

5.1. **Discrete spectrum eigenstates.** Let us explain how the Bloch solutions can be used to construct the discrete spectrum eigenstates of L. Our discussion is strictly confined to the Calogero–Moser operator (5.13). We take a purely imaginary τ, this ensures that the potential in (5.13) is real-valued for $x \in \mathbb{R}^n$. The Calogero–Moser operator L is defined on a dense subset of $L^2(\mathbb{R}^n)$ and it is self-adjoint only formally, and its Bloch solutions are singular. It has square-integrable eigenstates, though. Namely, let $\psi = \psi_{k,\gamma}$ be one of the double-Bloch solutions constructed in the previous section. Given such a ψ, let us symmetrize it as follows:

$$(5.23) \qquad \Psi(x) = \sum_{w \in W} \varepsilon_m(w) \det w \, \psi(wx) \,,$$

where W is the Weyl group of the root system R and ε_m is the character (5.15). The Calogero–Moser operator L is W-invariant, thus the constructed Ψ will be again its eigenfunction (by the same reason, it will be an eigenfunction for all commuting

operators L_i). A priori, Ψ might have poles in $\mathbb{R}^n$ along the hyperplanes $\langle \alpha, x \rangle = c$, $c \in \mathbb{Z}$. However, it is easy to see that Ψ has no poles along the hyperplanes $\langle \alpha, x \rangle = 0$. This follows immediately from the properties (5.1) of ψ. To avoid the appearance of singularities on other hyperplanes $\langle \alpha, x \rangle = c$, one has to impose the condition that all the terms $\psi(wx)$ in the sum (5.23) have the same Bloch–Floquet multipliers with respect to a shift $x \mapsto x + l$ with $l \in \mathcal{L} = P^\vee$. This means that $\exp\langle k, l \rangle = \exp\langle wk, l \rangle$ for all $w \in W$ and $l \in P^\vee$, which in its turn implies that k belongs to the lattice $2\pi i P$. So, we have the following result.

Proposition 5.6. *Let L be the Calogero–Moser operator (5.13). Then for any point (k, γ) of its Bloch–Hermite variety which satisfies an additional condition $k \in 2\pi i P$ (with P being the weight lattice for R), the corresponding function (5.23) (if nonzero) will be a nonsingular in $\mathbb{R}^n$ eigenfunction of the Calogero–Moser operator (5.13) and of the higher operators $L_2, \ldots, L_n$.*

By construction, Ψ vanishes along the hyperplanes $\langle \alpha, x \rangle \in \mathbb{Z}$, and it gets a factor of $(-1)^{m_\alpha + 1}$ under the orthogonal reflection with respect to such a hyperplane. Since these are the reflection hyperplanes of the affine Weyl group of R, they cut $\mathbb{R}^n$ into its fundamental domains (alcoves), so the restriction of Ψ to each alcove will be, essentially, the same. We can restrict Ψ to any alcove, extending it by zero outside, and this gives us a finitely supported smooth eigenfunction of L (notice that in the complex domain it still has poles). We see from this that the discrete spectrum of L in $L^2(\mathbb{R}^n)$ is infinitely degenerate (one says that the spectral problem for L splits into identical spectral problems on each of the alcoves). Morally, this is the reason why one should expect the same spectrum considering L not on $L^2(\mathbb{R}^n)$ but on the space $L^2(T)^W$ of W-invariant functions on the torus $T = \mathbb{R}^n/Q^\vee$, as in [46]. The latter case is simpler from the technical point of view, since the operator L is essentially self-adjoint on $L^2(T)^W$, see [46] for the details.

In [46] Komori and Takemura considered the elliptic Calogero–Moser problems as a perturbation (in τ) of the trigonometric case $\tau = +i\infty$, and Theorem 3.7 of [46] claims that for sufficiently small $p = e^{2\pi i \tau}$ the family of eigenfunctions (Jack polynomials) which corresponds to $p = 0$, admits analytic continuation in p, and the resulting functions will give rise to a complete orthogonal family of eigenfunctions of L in $L^2(T)^W$. One can show that our family in the limit $\tau \to +i\infty$ specializes to the Jack polynomials. Comparing this with the previous discussion, we conclude that our family must coincide with the one considered in [46].

6. Calogero–Moser model of B_2 type

In this section we consider the following 2-dimensional Schrödinger operator

$$(6.1) \qquad L = -\Delta + 2\wp(x_1) + 2\wp(x_2) + 4\wp(x_1 - x_2) + 4\wp(x_1 + x_2),$$

where $\wp(z) = \wp(z|\tau)$ is the Weierstrass $\wp$-function with the periods 1, τ (Im $\tau > 0$). Our goal is to calculate its double-Bloch eigenfunctions, i.e. such ψ that

$$(6.2) \qquad\qquad\qquad \psi(x + e_j) = \lambda_j \psi(x)$$

$$(6.3) \qquad\qquad\qquad \psi(x + \tau e_j) = \mu_j \psi(x) \quad (j = 1, 2),$$

where (e_1, e_2) is the standard basis in $\mathbb{C}^2$ and $(\lambda_1, \lambda_2, \mu_1, \mu_2)$ are fixed Bloch–Floquet multipliers.

First we recall some standard definitions and formulas from the theory of theta-functions, see [43, 35]. Let $\theta\begin{bmatrix}\alpha\\\beta\end{bmatrix}$ be the one-dimensional theta-function (with characteristics), defined by the following series:

$$\theta\begin{bmatrix}\alpha\\\beta\end{bmatrix}(z|\tau) = \sum_{n\in\mathbb{Z}}\exp(\pi i(n+\alpha)^2\tau + 2\pi i(n+\alpha)(z+\beta)).$$

Notice that α and β are defined modulo 1:

$$\theta\begin{bmatrix}\alpha+1\\\beta\end{bmatrix} = \theta\begin{bmatrix}\alpha\\\beta\end{bmatrix}, \quad \theta\begin{bmatrix}\alpha\\\beta+1\end{bmatrix} = e^{2\pi i\alpha}\theta\begin{bmatrix}\alpha\\\beta\end{bmatrix}.$$

Later we will need the following formula which can be easily derived from the definitions:

$$(6.4) \quad \theta\begin{bmatrix}\alpha_1\\0\end{bmatrix}(x_1|\tau)\theta\begin{bmatrix}\alpha_2\\0\end{bmatrix}(x_2|\tau) = \theta\begin{bmatrix}\alpha_+\\0\end{bmatrix}(x_+|2\tau)\theta\begin{bmatrix}\alpha_-\\0\end{bmatrix}(x_-|2\tau)$$

$$+ \theta\begin{bmatrix}\alpha_+ + \frac{1}{2}\\0\end{bmatrix}(x_+|2\tau)\theta\begin{bmatrix}\alpha_- + \frac{1}{2}\\0\end{bmatrix}(x_-|2\tau),$$

where $\alpha_\pm = \frac{1}{2}(\alpha_1 \pm \alpha_2)$, $x_\pm = x_1 \pm x_2$.

We will mostly use $\theta\begin{bmatrix}1/2\\1/2\end{bmatrix}$ which we will denote simply by $\theta(z)$, which will always stand for the odd Jacobi theta function (5.4).

According to the previous section, ψ must have the form

$$(6.5) \qquad \psi = \frac{\Phi(x_1, x_2)}{\theta(x_1|\tau)\theta(x_2|\tau)\theta(x_1 - x_2|\tau)\theta(x_1 + x_2|\tau)}.$$

Here Φ is nonsingular in $\mathbb{C}^2$. The translation properties for ψ easily translate into the properties of Φ:

$$\Phi(x + e_j) = -\lambda_j\Phi(x),$$

$$\Phi(x + \tau e_j) = -\mu_j e^{-3\pi i\tau - 6\pi i x_j}\Phi(x).$$

Standard considerations from the theory of theta-functions show that the linear space of functions with these properties has dimension 9 and Φ must be of the form

$$(6.6) \quad \Phi = \exp(K_1 x_1 + K_2 x_2)\sum_{0\le i,j\le 2}c_{ij}\theta\begin{bmatrix}i/3\\0\end{bmatrix}(3x_1 + \gamma_1|3\tau)\theta\begin{bmatrix}j/3\\0\end{bmatrix}(3x_2 + \gamma_2|3\tau),$$

where c_{ij} are arbitrary constants and parameters γ_j, K_j relate to λ_j, μ_j as follows:

$$(6.7) \qquad\qquad \lambda_j = -e^{K_j}, \quad \mu_j = -e^{-2\pi i\gamma_j + K_j\tau}.$$

Remark 6.1. The shifting

$$(6.8) \qquad\qquad\qquad\qquad \gamma_j \mapsto \gamma_j + 1$$

does not change the space (6.6), the same applies to the shifts

$$(6.9) \qquad\qquad\qquad (K_j, \gamma_j) \mapsto (K_j + 2\pi i, \gamma_j + \tau).$$

Conversely, for any given λ_j, μ_j the corresponding (γ_j, K_j) are determined uniquely modulo shifts (6.8)–(6.9).

Now, in accordance with Proposition 5.1, we impose the following 'vanishing' conditions on Φ:

$$(6.10) \qquad \partial_1 \Phi \equiv 0 \quad \text{for } x_1 = 0 \,,$$

$$(6.11) \qquad \partial_2 \Phi \equiv 0 \quad \text{for } x_2 = 0 \,,$$

$$(6.12) \qquad (\partial_1 + \partial_2)\Phi \equiv 0 \quad \text{for } x_1 + x_2 = 0 \,,$$

$$(6.13) \qquad (\partial_1 - \partial_2)\Phi \equiv 0 \quad \text{for } x_1 - x_2 = 0 \,.$$

As we will see below, for a certain 2-dimensional surface in 4-dimensional space of parameters (k_j, a_j), the conditions (6.10)–(6.13) cut a one-dimensional subspace in 9-dimensional space (6.6). Thus, the corresponding ψ will be an eigenfunction for L automatically.

To determine the corresponding (K_j, γ_j), let us rewrite Φ using (6.4) and making identification $\theta\begin{bmatrix} \alpha+1 \\ 0 \end{bmatrix} = \theta\begin{bmatrix} \alpha \\ 0 \end{bmatrix}$:

$$\Phi = e^{K_+ x_+ + K_- x_-} \sum_{0 \le l,m \le 2} \widetilde{c}_{lm} \left\{ \theta\begin{bmatrix} l/3 \\ 0 \end{bmatrix}(3x_+ + \gamma_+|6\tau)\theta\begin{bmatrix} m/3 \\ 0 \end{bmatrix}(3x_- + \gamma_-|6\tau) \right.$$
$$\left. + \theta\begin{bmatrix} l/3 + 1/2 \\ 0 \end{bmatrix}(3x_+ + \gamma_+|6\tau)\theta\begin{bmatrix} m/3 + 1/2 \\ 0 \end{bmatrix}(3x_- + \gamma_-|6\tau) \right\} \,,$$

where $K_\pm = \frac{1}{2}(K_1 \pm K_2)$, $\gamma_\pm = \gamma_1 \pm \gamma_2$ and

$$(6.14) \qquad \widetilde{c}_{lm} = c_{ij} \quad \text{with} \quad i \equiv l + m \pmod 3, \; j \equiv l - m \pmod 3 \,.$$

It is easy to see now that (6.12) leads to six linear equations on $\widetilde{c}_{lm}$ of the form

$$\sum_{l=0}^{2} A_l \widetilde{c}_{lm} = 0, \qquad \sum_{l=0}^{2} B_l \widetilde{c}_{lm} = 0 \qquad (m = 0, 1, 2)$$

for certain explicitly given $A = (A_l)$, $B = (B_l)$. For generic parameters γ_1, γ_2 the vectors A, B will be linearly independent. Therefore, these 6 equations determine the 2-dimensional kernel of the matrix $\widetilde{C} = (\widetilde{c}_{lm})$. Similarly, (6.13) gives six more equations for $\widetilde{c}_{lm}$, which determine the cokernel of $\widetilde{C}$. Thus, for any K_1, K_2 and generic γ_1, γ_2 the vanishing conditions (6.12)–(6.13) determine $\widetilde{c}_{lm}$ (and, hence, Φ) uniquely up to a common factor. In principle, it is straightforward to write down explicit expressions for the coefficients c_{ij} but they are cumbersome and not very useful. However, there is a better way of getting an expression for Φ, by taking a limit $\omega \to 0$ in the formula for the difference case, see (7.7) below. It turns out that Φ has the form

$$(6.15) \qquad \Phi = \frac{e^{(k,x)}}{\theta(a_1|\tau)\theta(a_2|\tau)} \sum_{0 \le i,j \le 2} b_{ij}(k_1 + k_2)^i (k_1 - k_2)^j \,,$$

where the parameters k_1, k_2 and a_1, a_2 relate to K_j, γ_j as

$$(6.16) \qquad k_j = K_j + \pi i \,, \qquad a_j = \gamma_j - (1+\tau)/2 \,.$$

The coefficients b_{ij} depend on x and a_1, a_2 and are given by the following recipe. Let us introduce formal commutative variables A, B, C, D. We also need the following scalar λ depending on τ:

$$\lambda := \theta'''(0|\tau)/\theta'(0|\tau) \,.$$

Now introduce U, V as $U := A + B - C$, $V := A + B - D$ and put

$$b_{22} = 1, \quad b_{21} = 2U, \quad b_{12} = 2V,$$

(6.17)
$$b_{20} = -\lambda + U^2, \quad b_{02} = -\lambda + V^2, \quad b_{11} = 4UV,$$

$$b_{10} = 2V(-\lambda + U^2), \quad b_{01} = 2U(-\lambda + V^2),$$

$$b_{00} = (-\lambda + U^2)(-\lambda + V^2).$$

After that one opens the brackets, so each of b_{ij} becomes a sum of monomials in A, B, C, D with scalar coefficients, and then replaces each monomial using the following rule:

(6.18) $\quad c A^p B^q C^r D^s \longrightarrow c \theta^{(p)}(x_1 + a_1)\theta^{(q)}(x_2 + a_2)\theta^{(r)}(x_1 - x_2)\theta^{(s)}(x_1 + x_2)$.

Here $\theta = \theta(z|\tau)$, as before, denotes the odd Jacobi theta function, and the upper index in brackets refers to taking derivatives in z. We treat a scalar as a multiple of $A^0 B^0 C^0 D^0$ assuming, as usual, that $f^{(0)} = f$. To illustrate this, we present below some first of the coefficients:

$$b_{22} = \theta(x_1 + a_1)\theta(x_2 + a_2)\theta(x_1 - x_2)\theta(x_1 + x_2),$$

$$b_{21} = 2\theta'(x_1 + a_1)\theta(x_2 + a_2)\theta(x_1 - x_2)\theta(x_1 + x_2) -$$

(6.19)
$$2\theta(x_1 + a_1)\theta'(x_2 + a_2)\theta(x_1 - x_2)\theta(x_1 + x_2) -$$

$$2\theta(x_1 + a_1)\theta(x_2 + a_2)\theta_1'(x_1 - x_2)\theta(x_1 + x_2),$$

$$b_{20} = -\lambda\theta(x_1 + a_1)\theta(x_2 + a_2)\theta(x_1 - x_2)\theta(x_1 + x_2) + \ldots$$

Proposition 6.2. *For any K_1, K_2 and generic γ_1, γ_2 there is a unique (up to a constant factor) function $\Phi(x)$ of the form (6.6) with the properties (6.10)–(6.13). It is described by the formulas (6.15)–(6.18) above.*

To prove the formula (6.15), one goes to the limit $\omega \to 0$ in the formula (7.7) from the next section, picking up the first nonzero term (of order 6 in ω).

Formulas (6.15)–(6.18) fix the dependence of $\Phi(x)$ on 4 parameters a_1, a_2, k_1, k_2. Let us consider now the translation properties of Φ regarded as a function of these parameters. Recall that for generic a_1, a_2 the function Φ was determined uniquely up to a factor by (6.6) and (6.12)–(6.13). Thus, it follows immediately from Remark 6.1 that under the shifts (6.8)–(6.9) Φ must remain the same, up to a factor independent on x. To find this factor, it is sufficient to look at the formula (6.19) for the leading coefficient b_{22}. As a result, we conclude that the function Φ, given by formulas (6.6), (6.15)–(6.18) is invariant with respect to the shifts (6.8)–(6.9):

(6.20) $\qquad \Phi(a_1 + 1, a_2, k_1, k_2) = \Phi(a_1, a_2 + 1, k_1, k_2) = \Phi(a_1, a_2, k_1, k_2)$,

(6.21) $\Phi(a_1 + \tau, a_2, k_1 + 2\pi i, k_2) = \Phi(a_1, a_2 + \tau, k_1, k_2 + 2\pi i) = \Phi(a_1, a_2, k_1, k_2)$.

Now let us find the interrelations between the parameters a_j, k_j which will guarantee two remaining vanishing conditions (6.10)–(6.11). Let G_1 and G_2 denote the derivatives $\partial_1 \partial_2 \Phi$ and $\partial_1 \partial_2^3 \Phi$ evaluated at $x_1 = x_2 = 0$:

(6.22) $\qquad G_1 = \dfrac{\partial^2 \Phi}{\partial x_1 \partial x_2}(0, 0), \qquad G_2 = \dfrac{\partial^4 \Phi}{\partial x_1 \partial x_2^3}(0, 0).$

Thus defined G_1, G_2 will be regarded as functions of the parameters a_1, a_2, k_1, k_2. Consider now the following two equations on these 4 parameters:

(6.23) $\qquad\qquad\qquad\qquad G_1 = 0, \quad G_2 = 0.$

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It is clear that conditions (6.10) imply both of the equations (6.23). Indeed, they guarantee that the function

$$(6.24) \qquad f(t) = \partial_1 \Phi(0, t)$$

is identically zero, in particular, $f'(0) = G_1 = 0$ and $f'''(0) = G_2 = 0$.

More interestingly, (6.23) are 'almost' equivalent to (6.10). To see this, note that the function (6.24) has the following translation properties in t:

$$f(t + 1) = e^{k_2} f(t),$$

$$f(t + \tau) = e^{k_2 \tau - 2\pi i (3t + a_2) - 3\pi i \tau} f(t).$$

From (6.12)–(6.13) we know that

$$(\partial_1 \pm \partial_2) \Phi(0, 0) = 0.$$

This gives that $f(0) = \partial_1 \Phi(0, 0) = 0$, while the first equation in (6.23) gives that $f'(0) = 0$. Together with the translation properties above this implies that f is proportional to the following theta function:

$$e^{k_2 t} \theta(t + a_2 | \tau) [\theta(t|\tau)]^2.$$

This function has nonzero third derivative at $t = 0$ as soon as

$$(6.25) \qquad k_2 \theta(a_2 | \tau) + \theta'(a_2 | \tau) \neq 0.$$

Thus, the conditions $f(0) = f'(0) = f'''(0) = 0$ imply that f is identically zero provided that (6.25) is true. The outcome is the following: for all a_1, a_2, k_1, k_2 satisfying the condition (6.25) the equations (6.23) imply (6.10).

Our next remark is that for any a_1, a_2, k_1, k_2 we have the relation $\partial_1 \partial_2^3 \Phi(0, 0) = \partial_1^3 \partial_2 \Phi(0, 0)$. This is due to the identity

$$4 \partial_1^3 \partial_2 \Phi - 4 \partial_1 \partial_2^3 \Phi = (\partial_1 + \partial_2)^3 (\partial_1 - \partial_2) \Phi - (\partial_1 - \partial_2)^3 (\partial_1 + \partial_2) \Phi$$

where the right-hand side vanishes at $x_1 = x_2 = 0$ due to (6.12)–(6.13). Thus, repeating the same arguments as above, we conclude that the equations (6.23) imply also (6.11), as soon as

$$(6.26) \qquad k_1 \theta(a_1 | \tau) + \theta'(a_1 | \tau) \neq 0.$$

As a result, we see that under assumptions (6.25)–(6.26) both vanishing conditions (6.10)–(6.11) are equivalent to one system (6.23). To remove the restrictions (6.25)–(6.26), let us consider equations (6.23) in more details.

First notice that the functions G_1, G_2 share the same translation properties (6.20)–(6.21) in (a_1, a_2, k_1, k_2) with Φ (since differentiating in x doesn't affect these properties). Notice also that G_1, G_2 are polynomials in k_1, k_2. Let us pass from k_1, k_2 to another variables p_1, p_2 as follows:

$$(6.27) \qquad p_1 = k_1 + \zeta(a_1), \quad p_2 = k_2 + \zeta(a_2),$$

where we used $\zeta = \zeta(z|\tau)$ to denote the logarithmic derivative of $\theta(z)$:

$$\zeta(z) = \frac{\theta'(z|\tau)}{\theta(z|\tau)}.$$

This is slightly different from the Weierstrass ζ-function.

Clearly, G_1, G_2 are still polynomials in p_1, p_2 with the coefficients depending on a_1, a_2. The translation properties (6.20)–(6.21) imply that the coefficients in these polynomials will be elliptic functions of a_1 and a_2. In fact, one can write down

G_1, G_2 quite explicitly. The following result follows from our calculations for the difference case from the next section.

Proposition 6.3. *The system $G_1 = G_2 = 0$ is equivalent to the following system:*

$$\text{(6.28)} \quad \begin{aligned} &p_1(p_2^3 + 3\zeta_2' p_2 + \zeta_2'') = p_2(p_1^3 + 3\zeta_1' p_1 + \zeta_1''), \\ &p_1(p_2^5 + 10\zeta_2' p_2^3 + 10\zeta_2'' p_2^2 + (5\zeta_2''' + 15(\zeta_2')^2)p_2 + \zeta_2'''' + 10\zeta_2'\zeta_2'') \\ &= p_2(p_1^5 + 10\zeta_1' p_1^3 + 10\zeta_1'' p_1^2 + (5\zeta_1''' + 15(\zeta_1')^2)p_1 + \zeta_1'''' + 10\zeta_1'\zeta_1''), \end{aligned}$$

where ζ_1, ζ_2 stand for $\zeta(a_1)$ and $\zeta(a_2)$ while the prime denotes taking the derivative with respect to the corresponding variable. (Notice that $\wp(z) = -\zeta' + \text{const}$, so $\zeta'' = -\wp'$ and so on.)

From the discussion below will follow that for generic a_1, a_2 the system (6.28) has a finite number of solutions (p_1, p_2). Thus, we can think of (6.28) as a finite covering of the product $\mathcal{E} \times \mathcal{E}$ of two copies of an elliptic curve $\mathcal{E} = \mathcal{E}_\tau = \mathbb{C}/(\mathbb{Z} + \tau\mathbb{Z})$. In fact, the only (a_1, a_2) where the fiber is infinite are those with $a_1 = \pm a_2 \pmod{1, \tau}$. This corresponds to the following 'vertical' components of (6.28):

$$\text{(6.29)} \qquad \{a_1 = a_2, \ p_1 = p_2\}, \qquad \{a_1 = -a_2, \ p_1 = -p_2\}.$$

Another 'trivial' component is, obviously,

$$\text{(6.30)} \qquad \{p_1 = p_2 = 0\}.$$

If we delete these three components from (6.28), the remaining part will be, in fact, a 13-fold covering of $\dot{\mathcal{E}} \times \dot{\mathcal{E}}$. Since we deleted the component (6.30), the conditions (6.25)–(6.26) and, hence, (6.10)–(6.11) are satisfied on the remaining part. Thus, we arrive at the following theorem.

Theorem 6.4. *Let $\mathcal{C}$ be the finite covering of the product of two (punctured) elliptic curves which is obtained from (6.28) by deleting the components (6.29) and (6.30). Then $\mathcal{C}$ is the Hermite–Bloch variety for the operator (6.1) and a double-Bloch solution $\psi(x)$ corresponding to a point (a_1, a_2, p_1, p_2) in $\mathcal{C}$ is given by the formulas (6.5), (6.15)–(6.18) and (6.27).*

We still have to explain why $\mathcal{C}$ is a 13-fold covering. To this end let us consider a family of plane rational curves $\varphi : \mathbb{P}^1 \to \mathbb{P}^2$ of degree 5, depending on a parameter $a \in \mathcal{E} = \mathbb{C}/\mathbb{Z} + \tau\mathbb{Z}$ and defined as follows: if $a \in \mathcal{E}$ and $u = (u_0 : u_1) \in \mathbb{P}^1$ then

$$\varphi(a, u) = (\varphi_0 : \varphi_1 : \varphi_2), \quad \text{where}$$

$$\varphi_0 = u_1 u_0^4,$$

$$\varphi_1 = u_1^3 u_0^2 + 3\zeta'(a)u_1 u_0^4 + \zeta''(a)u_0^5,$$

$$\varphi_2 = u_1^5 + 10\zeta'(a)u_1^3 u_0^2 + (5\zeta'''(a) + 15(\zeta'(a))^2)u_1 u_0^4 + (\zeta''''(a) + 10\zeta'(a)\zeta''(a))u_0^5.$$

Then the solutions (p_1, p_2) of (6.28) correspond to the intersection points of two curves $C_1 = \varphi(a_1, \cdot)$, $C_2 = \varphi(a_2, \cdot)$ from our family. Namely, if $\varphi(a_1, u) = \varphi(a_2, v)$ then $p_1 = u_1/u_0$ and $p_2 = v_1/v_0$ obviously satisfy (6.28) and vice versa, provided $p_1, p_2 \neq 0$. We should, however, exclude from consideration points with $p_1, p_2 = \infty$. Namely, all the curves from our family pass through $(0 : 0 : 1) = \varphi(a, \infty)$. It is a standard exercise in basic algebraic geometry to show that $\text{mult}(C_1 \cap C_2)$ at this point equals 12. In doing this local analysis, one immediately observes that the condition $\zeta(a_1) = \zeta(a_2)$ is necessary for C_1 and C_2 to coincide near the point $(0 : 0 : 1)$. This proves that the covering (6.28) is finite apart from the components

(6.29). After that Bezout's theorem tells us that the number of common points, apart from $(0:0:1)$, equals $5 \times 5 - 12 = 13$.

Remark 6.5. Operator (6.1) is symmetric under the Weyl group W of B_2, whose 8 elements act by permuting coordinates and/or changing their signs. This induces the action of W on Bloch solutions and, therefore, on the Hermite–Bloch variety (6.28). This action, in terms of (a_1, a_2, p_1, p_2), is generated by involutions $(a_1, a_2, p_1, p_2) \rightarrow (a_2, a_1, p_2, p_1)$ and $(a_1, a_2, p_1, p_2) \rightarrow (-a_1, a_2, -p_1, p_2)$.

6.1. **Algebraic integrability.** The operator L (6.1) is completely integrable. According to Theorem 4.1, it has a commuting operator of order four,

$$L_1 = \partial_1^2 \partial_2^2 + \dots .$$

Using Proposition 5.1, we see that our ψ is a common eigenfunction for L, L_1:

$$(6.31) \qquad\qquad L\psi = E\psi, \quad L_1\psi = E_1\psi, \quad L_2\psi = E_2\psi .$$

Here E, E_1 are some functions of the parameters a_1, a_2, k_1, k_2 which, in principle, can be calculated explicitly (though we didn't have enough energy to perform such a calculation).

In [44] it was shown that apart from L_1, there is another operator

$$L_2 = \partial_1^5 - 5\partial_1^3 \partial_2^2 + \dots$$

which commutes with L, L_1 (see [44] for the explicit expression for L_1, L_2). The existence of a fifth order quantum integral L_2 means in this case that the Schrödinger operator L is algebraically integrable. To see this directly, let us consider one more operator L_3, obtained from L_2 by interchanging x_1 and x_2. Then one easily checks that the common eigenspace (6.31) of L and L_1 is 8-dimensional, and for generic E and E_1 it is spanned by the double-Bloch solutions ψ, constructed previously. On the other hand, by proposition 5.1, each ψ will be an eigenfunction of L_2 and L_3 as well. So, the only thing to check is that the eigenvalues E_2, E_3 separate all 8 solutions of the system (6.31). This is enough to check in the trigonometric limit $\tau \rightarrow +i\infty$, which is not difficult.

Remark 6.6. We do not give the precise relation between the Hermite–Bloch variety and the spectral surface. To find such a relation, a careful analysis of the structure of the divisor at infinity is needed. Let us remark that in [45] two algebraic relations between the 4 operators $L, \dots, L_3$ were calculated explicitly. Thus, they determine a 2-dimensional affine algebraic variety in $\mathbb{C}^4$. However, it is not isomorphic to the spectral surface as an affine variety (though they are birationally equivalent). This can be seen already in the trigonometric limit $\tau \rightarrow +i\infty$, by using the information about the spectral variety from [10]. Namely, the results of [10] imply that these four operators $L, \dots, L_3$ are not enough to generate the whole commutative ring (which is isomorphic to the coordinate ring of the spectral surface).

6.2. **Spectrum of L.** Throughout this subsection we assume that the parameter τ is pure imaginary, so the potential $u(x)$ of the Schrödinger operator (6.1) is real-valued for $x \in \mathbb{R}^2$. Its singularities is the family of lines

$$(6.32) \qquad x_1 \in \mathbb{Z}, \quad x_2 \in \mathbb{Z}, \quad x_1 + x_2 \in \mathbb{Z}, \quad x_1 - x_2 \in \mathbb{Z} .$$

These lines cut $\mathbb{R}^2$ into triangles and the spectral problem for L splits into separate spectral problems for each triangle.

Let $\psi(x) = \psi(x; a_1, a_2, p_1, p_2)$ be a double-Bloch eigenfunction for L, which corresponds to a point (a_1, a_2, p_1, p_2) of the surface (6.28) in accordance with the formulas (6.5), (6.15)–(6.18) and (6.27). Given such a ψ, let us symmetrize it in the following way:

$$(6.33) \qquad \Psi(x) = \sum_{w \in W} \psi(wx),$$

where W denotes the Weyl group for the system B_2. To get a square-integrable eigenfunction, according to Proposition 5.6, one takes $k \in 2\pi i P$, that is $k = (i\pi m, i\pi n)$ with integer m, n having the same parity. For such k the substitution of (6.27) into (6.28) leads to a system of (transcendental) equations on a_1, a_2, and by solving it one eventually finds the corresponding eigenfunctions. Note that because of the invariance of the system (6.28) (and of ψ) under the shifts (6.8)–(6.9), it is enough to look for the solutions (a_1, a_2) with a_i lying inside the fundamental parallelogram with the vertices $\pm(1 + \tau)/2$. Also, taking into account the Weyl group action, we can restrict ourselves to the dominant weights, i.e. $0 \le m \le n$.

Now let us consider the trigonometric limit $\tau \to +i\infty$, then one can show that for any m, n the corresponding system (6.28) will have the unique solution a_1, a_2 inside the fundamental parallelogram (at least, for sufficiently big τ). Moreover, if one fixes $k = (k_1, k_2)$ and takes then the limit $\tau \to +\infty$, then ψ will go to the Baker–Akhiezer function $\psi(k, x)$ considered in [42] (this can be seen directly from the formulas for ψ). Now, for the Baker–Akhiezer function $\psi(k, x)$ it is known (see Theorem 6.7 of [42]) that the formula (6.33) will produces all the Jack polynomials if

$$(6.34) \qquad k = 2\pi i(\lambda + \rho) \qquad \text{with } \lambda \in P_+ \quad \text{and } \rho = \frac{1}{2} \sum_{\alpha \in R_+} (m_\alpha + 1)\alpha.$$

For others $k \in 2\pi i P_+$ the symmetrized Ψ will be zero.

In our situation this means that the function $\Psi = \Psi_{m,n}$ defined by (6.33) will be non-zero as soon as

$$(6.35) \qquad n - 4 \ge m \ge 2, \qquad \text{with} \quad n \equiv m \ (\text{mod} 2).$$

For other $k \in 2\pi i P_+$ it will be zero in the trigonometric limit. But the result of [46] cited in Section 5.1 claims that the family of the eigenfunctions of L is analytic in $p = e^{\pi i \tau}$ and specializes to the Jack polynomials at $p = 0$. Hence, if $\Psi_{m,n} = 0$ in the trigonometric limit, it must be zero for all τ identically.

We conclude that the eigenfunctions $\Psi_{m,n}$ of L are labeled by m, n satysfying (6.35). In particular, the ground state corresponds to $(m, n) = (2, 6)$. The constructed solutions $\Psi_{m,n}$ will have second order zeros along the lines (6.32) and will be invariant under orthogonal reflections with respect to these lines. According to the results of [46], the resulting family is complete in $L^2(T)^W$ (see Section 5.1 above).

Remark 6.7. For certain (a_1, a_2, k_1, k_2) the corresponding Bloch solution ψ has a nontrivial symmetry in x, which must be a subgroup of the Weyl group W. Our formulas for ψ do not work directly for some of these cases, because of the presence of an extra component (6.29). Of particular interest are those of the points which correspond to the solutions which are double-(anti)periodic (in each of the variables x_1, x_2). These can be viewed as multidimensional analogues of the classical Lamé polynomials [43].

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7. Difference B_2 case

In this section we will generalize the results above to the following difference version of the operator (6.1):

$$(7.1) \qquad L = a_0 + a_+ T_1^{2\omega} + a_- T_1^{-2\omega} + b_+ T_2^{2\omega} + b_- T_2^{-2\omega},$$

where T_i^ϵ stands for a shift in x_i by ϵ, and the coefficients $a_\pm, b_\pm$ are

$$a_\pm = \frac{\theta(x_1 \mp \omega)\theta(x_1 + x_2 \mp 2\omega)\theta(x_1 - x_2 \mp 2\omega)}{\theta(x_1 \pm \omega)\theta(x_1 + x_2)\theta(x_1 - x_2)},$$

$$b_\pm = \frac{\theta(x_2 \mp \omega)\theta(x_1 + x_2 \mp 2\omega)\theta(x_1 - x_2 \pm 2\omega)}{\theta(x_2 \pm \omega)\theta(x_1 + x_2)\theta(x_1 - x_2)},$$

while a_0 has the form $a_0 = c_+ + c_- + d_+ + d_-$ with $c_\pm, d_\pm$ given by

$$c_\pm = \frac{\theta(2\omega)\theta(x_1 \pm 5\omega)\theta(x_1 + x_2 \mp 2\omega)\theta(x_1 - x_2 \mp 2\omega)}{\theta(4\omega)\theta(x_1 \pm \omega)\theta(x_1 + x_2)\theta(x_1 - x_2)},$$

$$d_\pm = \frac{\theta(2\omega)\theta(x_2 \pm 5\omega)\theta(x_1 + x_2 \mp 2\omega)\theta(x_1 - x_2 \pm 2\omega)}{\theta(4\omega)\theta(x_2 \pm \omega)\theta(x_1 + x_2)\theta(x_1 - x_2)}.$$

In all formulas $\theta(z) = \theta(z|\tau)$ is the odd Jacobi theta function (5.4).

This is a very special case of the so-called BC_n generalization of the quantum Ruijsenaars model [47]. In trigonometric case it has been introduced by Koornwinder [48]. Elliptic version was first suggested by van Diejen [49] and later extended in [50], where its complete integrability has been proven. This also can be viewed as an elliptic generalization of one of the Macdonald operators [51] for B_2. In what follows we assume that the parameter ω is generic. Note that the operator (6.1) can be restored (up to a certain gauge) in the limit $\omega \to 0$.

It is worth mentioning that coefficients of L are not periodic, so instead of (double-) Bloch solutions one should look for the eigenfunctions in a certain θ-functional space. Another way of putting it is to observe that L can be reduced to elliptic form using proper gauge. For instance, consider

$$\widetilde{L} = \delta^{-1} \circ L \circ \delta, \qquad \delta = \theta(x_1)\theta(x_2)\theta(x_1 + x_2)\theta(x_1 - x_2).$$

Then $\widetilde{L}$ will have elliptic coefficients, so we can look for its Bloch solutions $\psi(x)$. Correspondingly, $\Phi = \delta\psi$ will be an eigenfunction for L and it will have translation properties similar to those of δ. Abusing the language, below we refer to Φ as a Bloch solution for L.

7.1. Bloch solutions.
We are going to construct eigenfunctions of L similar to the differential case above. Our ansatz for Φ remains unchanged:

$$(7.2) \quad \Phi = \exp(K_1 x_1 + K_2 x_2) \sum_{0 \le i,j \le 2} c_{ij} \theta\begin{bmatrix} i/3 \\ 0 \end{bmatrix}(3x_1 + \gamma_1 | 3\tau) \theta\begin{bmatrix} j/3 \\ 0 \end{bmatrix}(3x_2 + \gamma_2 | 3\tau).$$

An analogue of the vanishing conditions (6.10)–(6.13) is dictated by the singularities of L and is the following:

$$(7.3) \qquad \Phi(\omega, x_2) \equiv \Phi(-\omega, x_2) \qquad\qquad \text{for all } x_2,$$

$$(7.4) \qquad \Phi(x_1, \omega) \equiv \Phi(x_1, -\omega) \qquad\qquad \text{for all } x_1,$$

$$(7.5) \qquad \Phi(x_1 + \omega, x_2 + \omega) \equiv \Phi(x_1 - \omega, x_2 - \omega) \qquad \text{for } x_1 + x_2 = 0,$$

$$(7.6) \qquad \Phi(x_1 + \omega, x_2 - \omega) \equiv \Phi(x_1 - \omega, x_2 + \omega) \qquad \text{for } x_1 - x_2 = 0.$$

We are going to show that for a certain two-dimensional variety in the space of parameters $\gamma_1, \gamma_2, K_1, K_2$ there is only one (up to a factor) such Φ. As a consequence, Φ will be an eigenfunction of L, due to a natural analogue of Proposition 5.1.

We start from conditions (7.5), (7.6). Using the formula (6.4) and repeating the arguments used in case $\omega = 0$, we obtain a linear system for c_{ij} and can see that (for generic γ_1, γ_2) it defines c_{ij} uniquely, up to a factor. However, solving this system leads to a very cumbersome formula. Instead, let us define Φ by the following formula:

$$(7.7) \quad \Phi = \exp(k_1 x_1 + k_2 x_2) \sum_{i,j} b_{ij} \theta(x_1 + a_1 + i\omega)\theta(x_2 + a_2 + j\omega)e^{\omega(ik_1 + jk_2)},$$

where the summation is taken over the following set of indices:

$$(i,j) = (0,4),(4,0),(0,-4),(-4,0),(2,2),(2,-2),(-2,-2),(-2,2),(0,0),$$

and the coefficients $b_{ij} = b_{ij}(x)$ look as follows:

$$b_{ij} = \beta_{ij}\theta\left(x_1 + x_2 - \frac{i+j}{2}\omega\right)\theta\left(x_1 - x_2 - \frac{i-j}{2}\omega\right)$$

with

$$\beta_{04} = \beta_{40} = \beta_{0,-4} = \beta_{-4,0} = (\theta(2\omega))^2$$
$$\beta_{22} = \beta_{2,-2} = \beta_{-2,-2} = \beta_{-2,2} = -\theta(2\omega)\theta(4\omega)$$
$$\beta_{00} = (\theta(4\omega))^2.$$

Proposition 7.1. *For any K_1, K_2 and generic γ_1, γ_2 there exists unique (up to a factor) function Φ of the form (7.2) satisfying conditions (7.5)–(7.6). It is given by the formula (7.7), where $k_j = K_j + \pi i$ and $a_j = \gamma_j - (1+\tau)/2$ $(j = 1, 2)$.*

To prove the proposition one first checks that this Φ has the needed translation properties in x_1, x_2, then an elementary check shows that conditions (7.5)–(7.6) are satisfied.

Let us turn now to conditions (7.3)–(7.4). First, let us remark that (7.5), (7.6) at $x = (0,0)$ imply that

$$(7.8) \qquad \Phi(\omega, \omega) - \Phi(-\omega, -\omega) = \Phi(\omega, -\omega) - \Phi(-\omega, \omega) = 0.$$

Introduce now

$$G_1 = \Phi(\omega, \omega) - \Phi(\omega, -\omega) - \Phi(-\omega, \omega) + \Phi(-\omega, -\omega),$$
$$G_2 = \Phi(\omega, -3\omega) - \Phi(-\omega, -3\omega) - \Phi(\omega, 3\omega) + \Phi(-\omega, 3\omega),$$

and consider the system

$$(7.9) \qquad\qquad\qquad G_1 = 0, \quad G_2 = 0.$$

Obviously, the vanishing condition (7.3) implies (7.9). Conversely, from the system (7.9) we deduce immediately that the function

$$f(t) = \Phi(\omega, t) - \Phi(-\omega, t)$$

satisfies the conditions $f(\omega) = f(-\omega)$ and $f(3\omega) = f(-3\omega)$. Together with (7.8) this gives that $f(\omega) = f(-\omega) = 0$. Since f is a theta function of order 3, it must have the form $f = \theta(t - \omega)\theta(t + \omega)g(t)$ with $g(3\omega) = g(-3\omega)$. Now, since g is a

theta function of the first order with known characteristics (expressed in terms of a_2, k_2), the condition $g(3\omega) = g(-3\omega)$ implies $g \equiv 0$ as soon as

$$(7.10) \qquad e^{6\omega k_2} \neq \frac{\theta(a_2 - 3\omega|\tau)}{\theta(a_2 + 3\omega|\tau)}.$$

The latter condition is a difference version of (6.25). Now let us collect some corollaries of (7.5)–(7.6):

$$\Phi(\omega, -3\omega) = \Phi(3\omega, -\omega), \quad \Phi(-\omega, -3\omega) = \Phi(-3\omega, -\omega),$$
$$\Phi(\omega, 3\omega) = \Phi(3\omega, \omega), \quad \Phi(-\omega, 3\omega) = \Phi(-3\omega, \omega).$$

Thus, G_2 can be rewritten as

$$G_2 = \Phi(3\omega, -\omega) - \Phi(-3\omega, -\omega) - \Phi(3\omega, \omega) + \Phi(-3\omega, \omega).$$

Hence, we can repeat the same arguments with respect to x_2-variable and conclude that the system (7.9) implies (7.4) as soon as

$$(7.11) \qquad e^{6\omega k_1} \neq \frac{\theta(a_1 - 3\omega|\tau)}{\theta(a_1 + 3\omega|\tau)}.$$

Summing up, we see that the system (7.9) implies both of the conditions (7.3)–(7.4) under assumptions (7.10)–(7.11).

To get rid of restrictions (7.10)–(7.11) let us calculate G_1, G_2. First, introduce the notation ξ_1, ξ_2 for

$$\xi_1 = e^{\omega k_1}, \quad \xi_2 = e^{\omega k_2}.$$

A direct substitution gives that

$$\Phi(\omega, \omega) = \beta_{0,-4}\theta(4\omega)\theta(-2\omega)\theta(a_1 + \omega)\theta(a_2 - 3\omega)\xi_1\xi_2^{-3} +$$
$$\beta_{-4,0}\theta(4\omega)\theta(2\omega)\theta(a_1 - 3\omega)\theta(a_2 + \omega)\xi_1^{-3}\xi_2 +$$
$$\beta_{-2,2}\theta(2\omega)\theta(2\omega)\theta(a_1 - \omega)\theta(a_2 + 3\omega)\xi_1^{-1}\xi_2^{3} +$$
$$\beta_{2,-2}\theta(2\omega)\theta(-2\omega)\theta(a_1 + 3\omega)\theta(a_2 - \omega)\xi_1^{3}\xi_2^{-1}.$$

In a similar way we calculate $\Phi(-\omega, \omega)$ and $G_1 = 2\Phi(\omega, \omega) - 2\Phi(-\omega, \omega)$. As a result, the equation $G_1 = 0$ takes the following form (up to a nonessential factor):

$$(7.12) \quad (\theta(a_1 + 3\omega)\xi_1^3 - \theta(a_1 - 3\omega)\xi_1^{-3})(\theta(a_2 + \omega)\xi_2 - \theta(a_2 - \omega)\xi_2^{-1})$$
$$= (\theta(a_1 + \omega)\xi_1 - \theta(a_1 - \omega)\xi_1^{-1})(\theta(a_2 + 3\omega)\xi_2^3 - \theta(a_2 - 3\omega)\xi_2^{-3}).$$

In a similar way one can compute G_2. It turns out that it is a linear combination of 8 terms of the form $\xi_1^{\pm 3}\xi_2^{\pm 5}$, $\xi_1^{\pm 5}\xi_2^{\pm 3}$ and 8 terms of the form $\xi_1^{\pm 1}\xi_2^{\pm 3}$, $\xi_1^{\pm 3}\xi_2^{\pm 1}$. Moreover, the combination of the last 8 terms is proportional to G_1, so we can get rid of them by subtracting G_1, this does not affect the system (7.9). After these transformations equation $G_2 = 0$ takes the following nice form:

$$(7.13) \quad (\theta(a_1 + 5\omega)\xi_1^5 - \theta(a_1 - 5\omega)\xi_1^{-5})(\theta(a_2 + 3\omega)\xi_2^3 - \theta(a_2 - 3\omega)\xi_2^{-3})$$
$$= (\theta(a_1 + 3\omega)\xi_1^3 - \theta(a_1 - 3\omega)\xi_1^{-3})(\theta(a_2 + 5\omega)\xi_2^5 - \theta(a_2 - 5\omega)\xi_2^{-5}).$$

Summarizing, we see that the system (7.9) is equivalent to the equations (7.12)–(7.13). These equations are obviously invariant under the transformations (6.8)–(6.9), in this way they define a covering over the product $\mathcal{E} \times \mathcal{E}$ of two elliptic curves $\mathcal{E} = \mathbb{C}/\mathbb{Z} + \tau\mathbb{Z}$. It has two 'vertical' components

$$(7.14) \qquad \{a_1 = a_2, \ \xi_1 = \xi_2\}, \qquad \{a_1 = -a_2, \ \xi_1 = (\xi_2)^{-1}\}.$$

Another 'trivial' component is given by

$$(7.15) \qquad \theta(a_1 + 3\omega)\xi_1^3 - \theta(a_1 - 3\omega)\xi_1^{-3} = \theta(a_2 + 3\omega)\xi_2^3 - \theta(a_2 - 3\omega)\xi_2^{-3} = 0 \,.$$

After deleting these three components, one gets a finite (in fact, 17-fold) covering of $\mathcal{E} \times \mathcal{E}$, let us denote it by $\mathcal{C}$. We can conclude now that for any point in $\mathcal{C}$ the corresponding function Φ will satisfy the vanishing conditions (7.3)–(7.6) and, hence, it will be an eigenfunction of the difference operator L.

Theorem 7.2. *Formulas* (7.7) *and equations* (7.12)–(7.13) *describe the (double-) Bloch eigenfunctions of the difference operator* (7.1). *The Bloch–Hermite variety* $\mathcal{C}$, *which is obtained by deleting components* (7.14)–(7.15) *from the variety* (7.12)–(7.13), *is a* 17*-fold covering of the product* $\mathcal{E} \times \mathcal{E}$ *of two elliptic curves.*

As a corollary, considering the limit $\omega \to 0$ we can calculate explicitly the Hermite–Bloch variety for the operator (6.1). Namely, one picks up the terms of order 4 and 6 in ω in equation (7.12).

Corollary 7.3. *In the limit* $\omega \to 0$ *the system* (7.12)–(7.13) *goes to* (6.28).

The only thing we still have to explain is why the degree of the covering is 17. To this end, let us define a family of plane rational curves $\varphi : \mathbb{P}^1 \to \mathbb{P}^2$ of degree 5, depending on parameter $a \in \mathcal{E}$. Namely, for $a \in \mathcal{E}$ and $u = (u_0 : u_1) \in \mathbb{P}^1$ put

$$\varphi(a, u) = (\varphi_0 : \varphi_1 : \varphi_2), \quad \text{where}$$

$$\varphi_0 = \frac{u_0^2 u_1^3 \theta(a + \omega)\theta(a - \omega/2)}{\theta(a + \omega/2)} - \frac{u_0^3 u_1^2 \theta(a - \omega)\theta(a + \omega/2)}{\theta(a - \omega/2)},$$

$$\varphi_1 = \frac{u_0 u_1^4 \theta(a + 3\omega)\theta^3(a - \omega/2)}{\theta^3(a + \omega/2)} - \frac{u_0^4 u_1 \theta(a - 3\omega)\theta^3(a + \omega/2)}{\theta^3(a - \omega/2)},$$

$$\varphi_2 = \frac{u_1^5 \theta(a + 5\omega)\theta^5(a - \omega/2)}{\theta^5(a + \omega/2)} - \frac{u_0^5 \theta(a - 5\omega)\theta^5(a + \omega/2)}{\theta^5(a - \omega/2)}.$$

Then the solutions (ξ_1, ξ_2) of (6.28) correspond to the intersection points of two curves $C_1 = \varphi(a_1, \cdot)$, $C_2 = \varphi(a_2, \cdot)$ from our family. Namely, if $\varphi(a_1, u) = \varphi(a_2, v)$ then ξ_1, ξ_2 with

$$(\xi_1)^2 = \frac{u_1 \theta^2(a_1 - \omega/2)}{u_0 \theta^2(a_1 + \omega/2)} \quad \text{and} \quad (\xi_2)^2 = \frac{v_1 \theta^2(a_2 - \omega/2)}{v_0 \theta^2(a_2 + \omega/2)}$$

clearly satisfy (7.12)–(7.13) and vice versa, provided (7.10)–(7.11). We should, however, exclude from consideration points with $\xi_1, \xi_2 = 0, \infty$ since $\xi_i = e^{\omega k_i}$. Namely, all the curves from our family pass through $(0 : 0 : 1) = \varphi(a, 0) = \varphi(a, \infty)$. A little difference with $\omega = 0$ case is that now we have $\mathrm{mult}\,(C_1 \cap C_2) = 8$ at this point. By Bezout's theorem, the number of intersection points of C_1, C_2, apart from $(0 : 0 : 1)$, equals $5 \times 5 - 8 = 17$.

Remark 7.4. Note that for given ξ_1^2, ξ_2^2 the corresponding quasimomenta k_1, k_2 seem to be non-unique, with the ambiguity of adding some multiple of $i\pi/\omega$. However, this would result in multiplying Φ by $e^{i\pi x_1/\omega}, e^{i\pi x_2/\omega}$ which are quasi-constant on the lattice $2\omega\mathbb{Z}^2$. Thus, this leads to the same eigenfunction, so the constructed Bloch solutions are in one-to-one correspondence with the points of the surface $\mathcal{C}$.

Remark 7.5. It is clear that the Weyl group action on $\mathcal{C}$ is generated by two involutions

$$(a_1, \xi_1) \to (-a_1, \xi_1^{-1}) \quad \text{and} \quad (a_1, \xi_1) \leftrightarrow (a_2, \xi_2) \,.$$

7.2. **Structure of the solution space.** As we mentioned above, the difference operator (7.1) is completely integrable, i.e. there exists another difference operator L_1 which commutes with L. It is given by the following expression [49, 50]:

$$(7.16) \qquad L_1 = c_{++}T_1^\omega T_2^\omega + c_{+-}T_1^\omega T_2^{-\omega} + c_{-+}T_1^{-\omega}T_2^\omega + c_{--}T_1^{-\omega}T_2^{-\omega},$$

where the coefficients $c_{\epsilon_1,\epsilon_2}$ look as follows (we treat $\pm$ as ± 1):

$$c_{\epsilon_1,\epsilon_2} = \frac{\theta(x_1 - \omega\epsilon_1)\theta(x_2 - \omega\epsilon_2)\theta(x_1 + x_2 - 2\omega(\epsilon_1 + \epsilon_2))\theta(x_1 - x_2 - 2\omega(\epsilon_1 - \epsilon_2))}{\theta(x_1)\theta(x_2)\theta(x_1 + x_2)\theta(x_1 - x_2)}.$$

Now let us consider the system of two partial difference equations:

$$(7.17) \qquad Lf = Ef, \quad L_1 f = E_1 f,$$

defined on the lattice $2\omega\mathcal{L}$ where

$$\mathcal{L} = \{(m,n) \mid m \pm n \in \mathbb{Z}\}.$$

More precisely, we fix generic $x^0 \in \mathbb{C}^2$ as a base point and regard a function f in (7.17) as being defined on $x^0 + 2\omega\mathcal{L} \subset \mathbb{C}^2$. The base point x^0 must be outside the singular locus of L, L_1, i.e. such that L, L_1 are nonsingular on $x^0 + 2\omega\mathcal{L}$.

The Bloch solutions Φ, constructed above, are common eigenfunctions of L and L_1. (The proof for L_1 is the same: the only thing to check is an analogue of Proposition 5.1.) Since L and L_1 are W-symmetric, each of the 8 functions $\Phi(wx)$ $(w \in W)$ will solve the system (7.17). We know that for generic point of the spectral surface X (thus, for generic E, E_1) all 8 functions $\Phi(wx)$ are linearly independent (as functions on $\mathbb{C}^2$), because they have different translation properties with respect to the shifts (6.8)–(6.9). Hence, their restriction to $x^0 + 2\omega\mathcal{L}$ also gives 8 linearly independent solutions of (7.17)(at least, for generic base point x^0). On the other hand, it is not difficult to see that any solution f is uniquely determined by its values at eight points $x^0 + \nu$ with the following ν:

$$\nu = (0,0), (\pm\omega, \omega), (\omega, -\omega), (\pm 2\omega, 0), (0, 2\omega), (\omega, 3\omega).$$

This implies that the dimension of the solution space of (7.17) is at most 8. Thus, we conclude that any solution of (7.17) (for generic E, E_1) is a linear combination of 8 Bloch solutions $\{\Phi(wx)\}_{w \in W}$.

Proposition 7.6. *The space of solutions of the system* (7.17) *has dimension* 8 *and for generic* E, E_1 *is generated by the Bloch solutions* $\Phi(wx)$ *(w $\in W$)*.

Remark 7.7. Above we associated a double-Bloch eigenfunction Φ to a solution (a_1, a_2, ξ_1, ξ_2) of the equations (7.12)–(7.13). Note that these equations are invariant under $\xi_j \to -\xi_j$, but this does not lead to another eigenfunction, since they will differ by a quasiconstant factor. Situation is different for the system (7.17), since it is defined on a different lattice. It is easy to see that (ξ_1, ξ_2) and $(-\xi_1, -\xi_2)$ still lead to the same solution modulo quasiconstants, the same is true for $(\xi_1, -\xi_2)$ and $(-\xi_1, \xi_2)$. The resulting two functions have the same eigenvalue E in (7.17), but opposite values of E_1. Thus, the Bloch variety for the system (7.17) is a double covering of the surface $\mathcal{C}$ introduced above.

We will not go into discussing the spectral properties of the difference operator L. See papers [52, 53] devoted to this rather delicate matter. Let us just remark on some special solutions analogous to the 'discrete spectrum' considered in section

6.2. Namely, let us consider the following anti-invariant solution of the system (7.17):

$$\Phi_{skew}(x) = \sum_{w \in W} (\det w) \Phi(wx) \,.$$

The vanishing conditions (7.3)–(7.6) imply that Φ_{skew} vanishes along lines $x_1 \pm x_2 = \pm 2\omega$ and $x_j = \pm\omega$. It also vanishes if $x_1 = \pm x_2$ and $x_j = 0$ due to anti-invariance. Let us require now for all 8 functions $\Phi(wx)$ to have the same Floquet–Bloch multipliers with respect to the shifts by e_1 and e_2, which is equivalent to the conditions

$$\exp(k_1) = \exp(k_2) = \pm 1 \,.$$

Then Φ_{skew} will vanish also along the shifted lines

$$x_1 \pm x_2 = m \,, m \pm 2\omega \,, \qquad x_j = n \,, n \pm \omega \quad (m, n \in \mathbb{Z}) \,.$$

In the limit $\omega \to 0$ these solutions go to those Ψ constructed in section 6.2, more precisely,

$$\omega^{-6}\Phi_{skew} \longrightarrow 64(\theta'(0))^2 \theta(a_1)\theta(a_2)\theta(x_1)\theta(x_2)\theta(x_1 + x_2)\theta(x_1 - x_2)\Psi \quad \text{as} \quad \omega \to 0 \,.$$

8. HIETARINTA OPERATOR AND ITS DISCRETIZATION

8.1. **Continuous case.** We consider now the Schrödinger operator (1.4) but first let us rescale the coordinates $x_i \to a_i x_i$, so instead of (1.4) we will consider

$$(8.1) \quad \begin{aligned} L = &-a_1^2\partial_1^2 - a_2^2\partial_2^2 - a_3^2\partial_3^2 \\ &+ 2(a_1^2 + a_2^2)\wp(x_1 - x_2) + 2(a_2^2 + a_3^3)\wp(x_2 - x_3) + 2(a_3^2 + a_1^2)\wp(x_3 - x_1) \,, \end{aligned}$$

where, as before, $\wp(z) = \wp(z|\tau)$ is the Weierstrass $\wp$-function and $a_1^2 + a_2^2 + a_3^2 = 0$. We are going to calculate the double-Bloch eigenfunctions of L. More specifically, we are looking for the solutions ψ of the equation $L\psi = E\psi$ with the following properties:

(i) ψ is of the form

$$(8.2) \qquad \psi(x) = \frac{\Phi(x)}{\theta(x_{12})\theta(x_{23})\theta(x_{31})} \exp(k_1 x_1 + k_2 x_2 + k_3 x_3) \,,$$

where $x_{ij} := x_i - x_j$, $\theta = \theta\begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix}$ and Φ is holomorphic in $\mathbb{C}^3$ and depends on the differences x_{ij} only, in other words, $(\partial_1 + \partial_2 + \partial_3)\Phi = 0$;

(ii) ψ has the following translation properties:

$$(8.3) \qquad \psi(x + e_j) = e^{k_j}\psi(x) \,, \qquad \psi(x + \tau e_j) = e^{\mu_j}\psi(x) \quad (j = 1, 2, 3) \,,$$

where (e_1, e_2, e_3) is the standard basis in $\mathbb{C}^3$.

It is not difficult to conclude that for fixed k_j, μ_j the conditions above determine a three-dimensional functional space, and the corresponding $\Phi(x)$ in (8.2) must be of the form

$$(8.4) \qquad \Phi = \sum_{l=0}^{2} c_l \theta(x_{12} + b_{12} + l\tau/3)\theta(x_{23} + b_{23} + l\tau/3)\theta(x_{31} + b_{31} + l\tau/3) \,,$$

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where c_0, c_1, c_2 are arbitrary constants and the parameters b_{12}, b_{23}, b_{31} are related to μ_j above in the following way:

$$e^{\mu_1} = e^{k_1 \tau + 2\pi i b_{31} - 2\pi i b_{12}},$$

(8.5) $$e^{\mu_2} = e^{k_2 \tau + 2\pi i b_{12} - 2\pi i b_{23}},$$

$$e^{\mu_3} = e^{k_3 \tau + 2\pi i b_{23} - 2\pi i b_{31}}.$$

This shows that the three-dimensional space (8.4) depends, essentially, on the pairwise differences of the parameters b_{lm} only. Thus, without loss of generality we may assume that

(8.6) $$b_{12} + b_{23} + b_{31} = 0.$$

In formulas below we will also use b_{21}, b_{32}, b_{13} under the convention that $b_{ij} = -b_{ji}$.

Now, in accordance with Proposition 5.1, we impose certain vanishing conditions on ψ which are motivated by the structure of the singularities of the operator (8.1). Namely, for any $i = 1, 2, 3$ consider the function $f(t) = \psi(x + ta_{i-1}^2 e_{i-1} - ta_{i+1}^2 e_{i+1})$ for x such that $x_{i-1} = x_{i+1}$ (we treat indices modulo 3, so $x_0 = x_3$). Our assumptions about ψ imply that for such x the function f will have a pole at $t = 0$, so its Laurent expansion will look as $f = a_{-1} t^{-1} + a_0 + a_1 t + \ldots$. The coefficients in this expansion depend on x. Let us require that $a_0 = 0$ for all x such that $x_{i-1} = x_{i+1}$. Using (8.2) one rewrites this condition as follows:

(8.7) $$a_{i-1}^2 k_{i-1} - a_{i+1}^2 k_{i+1} + F_i = 0,$$

(8.8) $$F_i := \frac{a_{i-1}^2 \partial_{i-1}\Phi - a_{i+1}^2 \partial_{i+1}\Phi}{\Phi} - a_{i-1}^2 \frac{\theta'(x_{i-1,i})}{\theta(x_{i-1,i})} + a_{i+1}^2 \frac{\theta'(x_{i+1,i})}{\theta(x_{i+1,i})},$$

with (8.7) to be valid for all x such that $x_{i-1} = x_{i+1}$.

The following lemma follows from Proposition 5.1.

Lemma 8.1. If ψ has the form (8.2), (8.4) and satisfies the vanishing conditions (8.7), then the same will be true for its image $\widetilde{\psi} = L\psi$ under the action of the operator (8.1).

As we will see below, for a certain three-dimensional subvariety in the space of the parameters k_j, b_{lm} the vanishing conditions cut a one-dimensional subspace in the space (8.4). Thus, the lemma ensures that the corresponding $\psi(x)$ will be an eigenfunction of L.

We may regard the restriction of the expression F_i on the plane $x_{i-1} = x_{i+1}$ as a function of $z = x_{i-1,i} = x_{i+1,i}$. It is easy to check then that F_i will be an elliptic function of z with periods $1, \tau$. So, first of all we have to choose the parameters b_{lm}, c_j in such a way that $F_i(z)$ would be non-singular. Let us assume that the parameters a_1, a_2, a_3 are generic enough, i.e. that $a_i^2 \neq a_j^2$. Then for F_i to be non-singular at $z = 0$ we need $\Phi(0) = 0$. This gives the following condition:

(8.9) $$\widetilde{c}_0 + \widetilde{c}_1 + \widetilde{c}_2 = 0, \qquad \widetilde{c}_l = c_l \theta(b_{12} + \frac{l\tau}{3})\theta(b_{23} + \frac{l\tau}{3})\theta(b_{31} + \frac{l\tau}{3}).$$

Now we note that

$$\Phi(z) := \Phi \mid_{x_{i-1} = x_{i+1}}$$

is a one-dimensional θ-function of order 2, hence it has two zeros (modulo $1, \tau$). First zero is $z = 0$ (due to condition (8.9)). An easy check shows that the second

zero is $z = b_{i,i-1} + b_{i,i+1}$. So, up to a constant factor,

$$\Phi(z) = \theta(z)\theta(z - b_{i,i-1} - b_{i,i+1}).$$

To get rid of a possible pole at $z = b_{i,i-1} + b_{i,i+1}$ in (8.8) we must require that $a_{i-1}^2 \partial_{i-1}\Phi - a_{i+1}^2 \partial_{i+1}\Phi = 0$ for $x_{i-1,i} = x_{i+1,i} = b_{i,i-1} + b_{i,i+1}$. This leads to the following relation:

$$(8.10) \qquad \sum_{l=0}^{2} \widetilde{c}_l (a_1^2 \zeta(b_{23} + \frac{l\tau}{3}) + a_2^2 \zeta(b_{31} + \frac{l\tau}{3}) + a_3^2 \zeta(b_{12} + \frac{l\tau}{3})) = 0.$$

Here and below $\zeta(z) := \frac{d}{dz} \log\theta(z)$. Notice that the relation (8.10) is symmetric with respect to indices $1, 2, 3$ (so we have just one condition instead of possible three!).

We use the relations (8.9), (8.10) to express (up to a common factor) the parameters c_l in terms of the parameters b_{ij}. These relations imply that each of F_i (8.8) is nonsingular in $z = x_{i-1,i} = x_{i+1,i}$, therefore they are some constants depending on c_l, b_{ij}. Thus, (8.7) leads to the expressions for the differences $a_{i-1}^2 k_{i-1} - a_{i+1}^2 k_{i+1}$ in terms of c_l and b_{lm}. One can check that the resulting system is always compatible (i.e. that $F_1 + F_2 + F_3 = 0$). This follows, for instance, from the compatibility of the system (8.18) below by going to the limit $\omega \to 0$. As a corollary, the formulas (8.2),(8.4), together with (8.9), (8.10) and (8.7) deliver the expression for the double-Bloch eigenfunctions of the operator L.

Finally, let us discuss the structure of the Hermite–Bloch variety of the operator (8.1). The double-Bloch solutions are parametrized by b_{12}, b_{23}, b_{31} with $b_{12} + b_{23} + b_{31} = 0$, and the corresponding k_1, k_2, k_3 are determined from (8.7). Denote by b and k the three-component vectors $b = (b_{12}, b_{23}, b_{31})$ and $k = (k_1, k_2, k_3)$. Then two different points in the parameter space (b, k) lead to the same solution iff the corresponding Floquet multipliers in (8.3) are the same. Taking into account relations (8.5), we conclude that the following transformations do not lead to another Bloch solution:

$$
\begin{aligned}
& b \to b + \varepsilon_1, && k \to k && (\varepsilon_1 = (2/3, -1/3, -1/3)) \\
(8.11) \quad & b \to b + \varepsilon_2, && k \to k && (\varepsilon_2 = (-1/3, 2/3, -1/3)) \\
& b \to b + \tau\varepsilon_1, && k \to k + 2\pi i(1, -1, 0) \\
& b \to b + \tau\varepsilon_2, && k \to k + 2\pi i(0, 1, -1).
\end{aligned}
$$

Thus, b is effectively represented by a point of a factor $\mathbb{C}^2/\mathcal{L} + \tau\mathcal{L}$ where $\mathbb{C}^2 = \{z_1 + z_2 + z_3 = 0\} \subset \mathbb{C}^3$ and the lattice $\mathcal{L}$ is generated by $\varepsilon_1, \varepsilon_2$. This factor is isomorphic to the product of two elliptic curves with parameter τ. Above each point b we have a complex line of double-Bloch solutions, because equations (8.7) determine k up to adding any multiple of $(a_1^{-2}, a_2^{-2}, a_3^{-2})$.

8.2. **Discrete case.** We keep the notation x_{ij} for $x_i - x_j$. The discrete version of the operator (8.1) looks as follows:

$$(8.12) \qquad D = \sum_{i=1}^{3} \frac{\theta(\omega)\theta(x_{i-1,i} + \omega a_i^2)\theta(x_{i,i+1} - \omega a_i^2)}{\theta(\omega a_i^2)\theta(x_{i-1,i})\theta(x_{i,i+1})} T_i^{\omega a_i^2},$$

where $a_1^2 + a_2^2 + a_3^2 = 0$ and T_i^ϵ stands for a shift by ϵ in x_i. Its rational version $\theta(z) = z$ was communicated to us by M.Feigin who found it to be dual (in bispectral sense) to the trigonometric version $\wp = \sin^{-2}$ of the Hietarinta operator.

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The difference operator (8.12) relates to (8.1) in the following way:

$$D = a_1^{-2} + a_2^{-2} + a_3^{-2} + \omega(\partial_1 + \partial_2 + \partial_3) + \frac{\omega^2}{2}(\text{const} - \widetilde{L}) + o(\omega^2) \quad \text{as} \quad \omega \to 0 \,,$$

where $\widetilde{L}$ is gauge-equivalent to L,

$$\widetilde{L} = \delta \circ L \circ \delta^{-1} \,, \qquad \delta = \theta(x_1 - x_2)\theta(x_2 - x_3)\theta(x_3 - x_1) \,.$$

Unlike L, the operator D is not periodic. As a result, instead of the double Bloch eigenfunctions, we will look for eigenfunctions with the translation properties similar to those of δ. Apart from that, our ansatz for the eigenfunctions φ of the operator D remains the same:

$$(8.13) \qquad \varphi = \exp(k_1 x_1 + k_2 x_2 + k_3 x_3)\Phi \,,$$

$$(8.14) \qquad \Phi = \sum_{l=0}^{2} c_l \theta(x_{12} + b_{12} + l\tau/3)\theta(x_{23} + b_{23} + l\tau/3)\theta(x_{31} + b_{31} + l\tau/3) \,,$$

$$(8.15) \qquad b_{12} + b_{23} + b_{31} = 0 \,.$$

The vanishing conditions now look as follows: for each $i = 1, 2, 3$

$$(8.16) \qquad F_i := \theta(x_{i,i-1} + \omega a_{i-1}^2)T_{i-1}^{\omega a_{i-1}^2}(\varphi) - \theta(x_{i,i+1} + \omega a_{i+1}^2)T_{i+1}^{\omega a_{i+1}^2}(\varphi) = 0$$

identically for all x with $x_{i+1} = x_{i-1}$.

We have then a straightforward analog of Lemma 8.1, so the same approach as above will give us the eigenfunctions for D.

Let us first formulate the result. Namely, we consider the following two conditions on the function $\Phi(x_1, x_2, x_3)$ given by (8.14):

$$(8.17) \qquad \Phi(\omega a_1^2, 0, -\omega a_2^2) = 0 \,, \qquad \Phi(-\omega a_2^2, 0, \omega a_3^2) = 0 \,.$$

This gives us two linear equations on c_l and we use them to express c_l (up to a factor) through b_{ij}.

Secondly, we impose the following three relations:

$$(8.18) \qquad
\begin{aligned}
e^{\omega a_1^2 k_1 - \omega a_3^2 k_3} &= \frac{\theta(\omega a_3^2)}{\theta(\omega a_1^2)} \frac{\Phi(0, 0, \omega a_3^2)}{\Phi(\omega a_1^2, 0, 0)} \\
e^{\omega a_2^2 k_2 - \omega a_1^2 k_1} &= \frac{\theta(\omega a_1^2)}{\theta(\omega a_2^2)} \frac{\Phi(\omega a_1^2, 0, 0)}{\Phi(0, \omega a_2^2, 0)} \\
e^{\omega a_3^2 k_3 - \omega a_2^2 k_2} &= \frac{\theta(\omega a_2^2)}{\theta(\omega a_3^2)} \frac{\Phi(0, \omega a_2^2, 0)}{\Phi(0, 0, \omega a_3^2)} \,.
\end{aligned}$$

We use these formulas to express k_1, k_2, k_3 through Φ. The solution is not unique, and in fact we have a one-parameter family of k_i. Altogether, formulas (8.17)–(8.18) fix the dependence of c_l and k_i and hence of φ on three parameters b_{ij} (related by (8.15)). The resulting family of functions $\varphi(x)$ depends on three parameters: two of b_{ij} and one more due to the freedom in resolving (8.18), see more comments below.

Theorem 8.2. *The formulas* (8.13)–(8.15) *and the relations* (8.17)–(8.18) *give a three-parameter family of eigenfunctions for the difference operator D.*

To prove the theorem, let us first notice that each of F_i in (8.16), being regarded as a function of $z = x_{i,i-1} = x_{i,i+1}$, is a one-dimensional theta-function of order 3, so if it doesn't vanish, it must have three zeros (modulo $1, \tau$). Moreover, a simple

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count shows that the sum of these zeros will be equal to $b_{i,i-1} + b_{i,i+1}$. On the other hand, a direct substitution into (8.16) shows that the relations (8.17) imply that F_2 vanishes for $z = -\omega a_1^2$ and $z = -\omega a_3^2$. Further, the first relation in (8.18) simply encodes the fact that F_2 vanishes at $z = 0$. Since the sum of these three zeros is ωa_2^2 which, generically, is not $b_{21} + b_{23}$, we conclude that $F_2(z)$ is zero identically.

At first glance it seems that we need to add four more conditions to ensure all the vanishing properties (8.16). Namely, one needs also

$$(8.19) \quad \Phi(0, \omega a_2^2, -\omega a_1^2) = \Phi(0, -\omega a_1^2, \omega a_3^2)$$
$$= \Phi(-\omega a_3^2, \omega a_2^2, 0) = \Phi(\omega a_1^2, -\omega a_3^2, 0) = 0 \,.$$

However, since Φ depends on the pairwise differences of x_i only, we will have that

$$\Phi(0, \omega a_2^2, -\omega a_1^2) = \Phi(-\omega a_2^2, -\omega a_2^2 + \omega a_2^2, -\omega a_2^2 - \omega a_1^2) = \Phi(-\omega a_2^2, 0, \omega a_3^2) = 0 \,.$$

In the same way other relations in (8.19) follow from (8.17).

This demonstrates that the three-parameter family constructed in the theorem satisfies the vanishing conditions (8.16), thus proving the theorem.

Finally, let us comment on the structure of the Hermite–Bloch variety. Similarly to the case $\omega = 0$ above, Bloch solutions are parametrized by $b = (b_{12}, b_{23}, b_{31})$ with $b_{12} + b_{23} + b_{31} = 0$. This determines the corresponding c_l by (8.17). After that $k = (k_1, k_2, k_3)$ are determined from (8.18). At this point we have certain freedom: if $k = (k_1, k_2, k_3)$ is a solution of (8.18), then any

$$k' = k + \frac{t}{\omega}(a_1^{-2}, a_2^{-2}, a_3^{-2}) + \frac{2\pi i}{\omega}(n_1 a_1^{-2}, n_2 a_2^{-2}, n_3 a_3^{-2})$$

with any $t \in \mathbb{C}$ and integer n_1, n_2, n_3 will be a solution, too. However, the last term is not essential since it results in multiplying Φ by a quasiconstant. For the same reason, the factor t in the second term is essential modulo $2\pi i$ only. Besides, we still have the translation invariance of Φ with respect to the transformations (8.11). Thus, the Hermite–Bloch variety is fibered over the product of two elliptic curves with the fibers isomorphic to $\mathbb{C}/2\pi i$.

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